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User Manual

CAN-Bus Tester 2

User Manual

CAN-Bus Tester 2

Version: 1.11

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Revision Overview

Date	Revision	Change(s)
2007-06-12	0	First version
2007-07-02	1	Various changes and error correction
2007-09-17	2	Protocol monitor description added
2007-11-12	3	Changes in "Ordering Information" and "Scope of Supply"
2008-01-15	4	Changes in "Ordering Information" and "Scope of Supply"
2009-05-28	5	Description of SAE J1939 and extended software amended
2010-01-25	6	Changes to new CI, new Function in Online Trigger
2010-06-07	7	Various changes and error correction
2011-05-20	8	Protocol monitor description extended, License management added
2012-05-14	9	Protocol monitor CANopen description extended
2015-04-01	10	Bit timing settings appended, enhanced measurement of the Disturbance-free voltage range
2015-10-23	11	Protocol monitor: symbolic decoding, Language switching

Note:

To use the CAN-Bus Tester 2, and for proper understanding of this manual, general knowledge of the field bus systems CAN, CANopen, DeviceNet and/or SAE J1939 are required.

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Terms, Definitions and Abbreviations

Baud rate	Data transfer rate (1 baud = 1 bit/s)
Evaluation period	44/64 (68%) of the bit width around the bit center, within which the disturbance-free voltage range is measured
Differential voltage	The voltage between the two signal lines CAN_H and CAN_L $U_D = U_{CAN\_H} - U_{CAN\_L}$
Disturbance-free voltage range	The term 'disturbance-free voltage range' is used for a voltage range of the differential voltage for a selected station over a frame, whose value does not fall below the nominal value over the evaluation period, not even for a short time.
DSO	Digital storage oscilloscope
Error frames	Active and passive error frames
Firmware	Software for a microprocessor
FPGA	Field Programmable Gate Array – programmable logic array for real-time functions
Segment	CAN bus segment terminated on both line ends using a resistor. A repeater inserted between line ends or connected to a line end also constitutes a segment termination.

1   Introduction

Thank you for purchasing CAN-Bus Tester 2 (CBT2)! You have acquired a tool supporting you in the start-up, analysis, monitoring and servicing/maintenance of your CAN bus plant.

Thanks to its wide range of applications, its high data transfer rate and above all through its high tolerance against interference in the field of plant automation, the CAN bus has been well established for the last few years. Nonetheless, even when starting up new plants, but also during operation, a large number of problems occur, resulting quickly in undesired and often expensive failures.

The CBT2 possesses a USB port for connection to a PC or a notebook. The clearly structured PC software provides straightforward operation of the device, the performance and evaluation of measurements, and supports you in the determination of error sources. Thanks to the integrated update option, you are already prepared for future extensions today. In addition the device is fitted with an integrated anti-theft system(Kensington Lock) which enables longterm measurements without supervision.

Wiring test

During the installation phase of CAN bus plants, the wiring test of the CBT2 is especially useful. With this test, it is possible to determine line short-circuits, line breaks, the bus termination, the loop resistances of the CAN line and the CAN power supply line, and the overall line length.

Measuring the physical bus characteristics

Analysis of the physical bus characteristics is another principal application of the CBT2. The causes for errors are often assumed to lie in the application software of the plant. Experience, however, has shown that most of the problems which occur are due to the use of inappropriate cable types, improper installation of the bus cables or disturbed driver functions at individual CAN bus stations. Typical error causes for a disturbed communication on the CAN bus are:

- missing or too many bus terminations
- too long bus lines and/or spurs, wrong cable types
- predamaged/defective bus drivers
- excessive contact resistances at the connectors/terminals due to aging/corrosion
- transient breaks on moving cables
- cable routing in environments subject to strong interference

Frames with a bad signal quality can only by detected via an analysis of the physical bus characteristics, permitting errors and their causes to be detected specifically. Early and regular checks already from start-up help locate fault sources before they lead to failures. Such checks increase the signal quality, the bus will work reliably and is more resistant to electromagnetic interference. Measurements at regular intervals are able to detect a gradual loss of quality before this leads to an error frame. Through preventive maintenance, it is possible to save the time and cost which would arise due to an unexpected plant standstill.

The CAN-Bus Tester 2 will help you efficiently in checking your CAN bus system and in finding faults and their causes. To this end, it provides the following scope of functions:

- Bus systems: CAN, CANopen, DeviceNet and SAE J1939
- Automatic detection of the baud rate used
- Automatic determination of all stations in the plant
- Bus station and measuring-point-related display of the signal conditions:
    - general quality level (0 ... 100 %)
    - disturbance-free voltage range
    - rising and falling edges
    - oscilloscope display with frame analysis for the complete message frame
- Real-time monitoring of physical and logical errors (online logger)
- Continuous monitoring of bus status, bus traffic load, error frames (active/passive errors)
- Real-time-capable hardware trigger output for user- or error-related analysis by way of ext. DSO
- Simple possibilities for comparisons with older measurements
- Detailed test report

Protocol Monitor CAN

The integrated "Protocol Monitor CAN" offers transmit and receive functions. The receive function is used to monitor and record either all or specially selected message frames. The transmit function enables a self-generated message frame to be sent. In this way, it is possible to parametrize CAN devices, for example.

Protocol Monitor CANopen

The CANopen protocol monitor serves as a monitoring tool for the analysis of CANopen-based systems. It interprets all received messages according to the CANopen specification. The messages are recognized as SDO, PDO, NMT, Sync, Time stamp, heartbeat and emergency objects and interpreted accordingly. The basis for the interpretation of CAN messages is the device description of the individual CANopen nodes. This description can be done by selecting the device profile, manually or by loading the corresponding EDS / DCF file.

A convenient filter based on node numbers (Node-IDs) or object types supports a targeted analysis of relevant data for the user.

Note:
The CANopen protocol monitor serves as a monitoring tool only and does not provide any data transmission function.

2 Start-up

2.1 Receiving inspection and testing

Carefully unpack the device immediately after receipt and check the consignment. If transport damage is to be assumed, inform the delivery agent within 72 hours and keep the packaging for inspection. The device must only be transported in its original or equivalent packaging.

Check the completeness of the consignment against Chapter 8 "Scope of Supply".

2.2 Acclimatizing the device

Before turning on the device, make sure that the device is at the same temperature as the room temperature. This will take max. 60 minutes.

2.3 Connecting the device

2.3.1 Design

Figure 1 shows all connections of the CBT2. The power supply is provided by the supplied AC/DC adapter (24 V) via an extra-low voltage socket. The internal contact is the plus pole. The "**ON**" LED lights green when the operating voltage is present.

Figure 1: Connections of the CBT2

The upper D-Sub 9 connector serves for connection to the plant CAN bus. The adapter board can be plugged at the lower D-Sub 9 connector and the CAN_L and CAN_H signal lines can be sampled for evaluation on a digital storage oscilloscope (DSO). A station-related trigger signal is available at the BNC socket. It can be connected to a DSO via the supplied BNC cable.

The connection to the PC or notebook is provided using a USB cable. During operation, the "**BUS STATUS**" LED indicates whether there is data traffic on the CAN bus. The colors correspond to those of the bus status LED in the application software (see Section 4.4.3.1 : "Bus status").

The triggering of a trigger pulse at the BNC socket is signaled by the "**TRIGGER**" LED lighting green. A red "**TRIGGER**" LED indicates that an error has been detected during the "Online Trigger" measurement (see Section 4.9 : "„Measurement Online Trigger" view").

2.3.2 Power supply

The desk power supply pack included in the scope of supply possesses a wide-range input for connection to mains voltages from 100 V to 240 V 50/60 Hz; it provides a d.c. voltage of 24 V. The CBT2 is ready for operation when the extra-low-voltage connector is plugged into the CBT2, the mains power cable into the power supply pack and the mains power plug into the mains power socket outlet. The "**ON**" LED on the device lights green. The "wings" of the extra-low-voltage connector must stand horizontally to be plugged into the CBT2. A 90° turn in the clockwise direction locks the plug in position.

The CBT2 can also be operated on a supply voltage which may be available optionally on the CAN cable, provided this voltage lies in the range from 9 V to 36 V. The "**ON**" LED on the device then lights yellow. If a mains power connection has been established, this mains power connection will be used for the power supply.

2.3.3 CAN bus connection

The plant to be tested is connected at the upper D-Sub 9 connector "**CAN**" on the CBT2 via an adapter cable. Various adapter cables are available and are included in the scope of delivery. The device can therefore immediately be connected to plants with the following bus connectors: D-Sub 9, Open style, M12, 7/8", SAE J1939-11 and SAE J1939-13.

2.3.4 Connecting to the digital storage oscilloscope

To display the signal quality of individual CAN bus stations on a DSO, the CBT2 generates a station-related trigger pulse. To this end, it is merely necessary to connect the BNC socket of the device to the external trigger input of the oscilloscope. The adapter board included in the scope of delivery is connected at the lower D-Sub 9 connector "**PROBE ADAPTER**", enabling simple sampling of the signals on the data lines CAN_H and CAN_L and of the shield potential with the oscilloscope probes.

For the sampling of the CAN signal, a differential sample is recommended (signal line CAN_H against CAN_L). If two simple probes are used (CH1 with CAN_H against shield and CH2 with CAN_L against shield), the storage oscilloscope must provide mathematics functions to be able to generate the difference (CH1 minus CH2).

2.3.5 Connecting the device to the PC

The CBT2 is connected to a PC or notebook via the "hot-pluggable" USB port. Before you connect the device to a PC or notebook, install the supplied software, since it includes the necessary USB driver (see Section 4.2 "Installing the software").

2.4 Prevention of accidents

When operating this test device, it is imperative to observe the general accident prevention regulations for the use of measuring instruments. The device must only be used in dry rooms.

3 Functions and Measuring Principle

3.1 The most important measuring functions

The CBT2 can measure and display the signal conditions of each CAN bus station. Any problems with the appropriate station or with the bus cabling can be inferred from the results of the signal quality. The CBT2 displays the following physical properties for each CAN bus station separately:

- General quality level (0 ... 100 %)
- Disturbance-free voltage range (minimum, interference-free differential voltage)
- Edge steepness (worst rising and falling edges of the message frame)
    - Oscilloscope display with frame analysis for the complete message frame

In addition to the physical measurements, the CBT2 provides online monitoring functions, i.e. the entire bus traffic is monitored and checked continuously. This includes monitoring of the bus traffic load and a counter for error frames (active and passive error frames).

The individual measuring functions are described in detail in the following subsections.

3.2 Measuring the physical bus characteristics

The CAN bus uses a difference signal, i.e. the actual data signal is transferred via two lines inverted to each other (CAN_H and CAN_L). The difference between these two lines generates the signal digitized by each CAN bus transceiver. Any faults occurring there can endanger the correct detection of the bit stream. The CBT2 provides an evaluation of the difference signal in the form of a general quality value, the disturbance-free voltage range and the edge steepness, as well as using the oscilloscope display. All these measurements are determined within a message frame.

Contrary to the quality level providing a general evaluation of the signal quality for the bus, the determination of the disturbance-free voltage range and of the edges, as well as the oscilloscope display are useful aids for targeted troubleshooting.

3.2.1 Disturbance-free voltage range
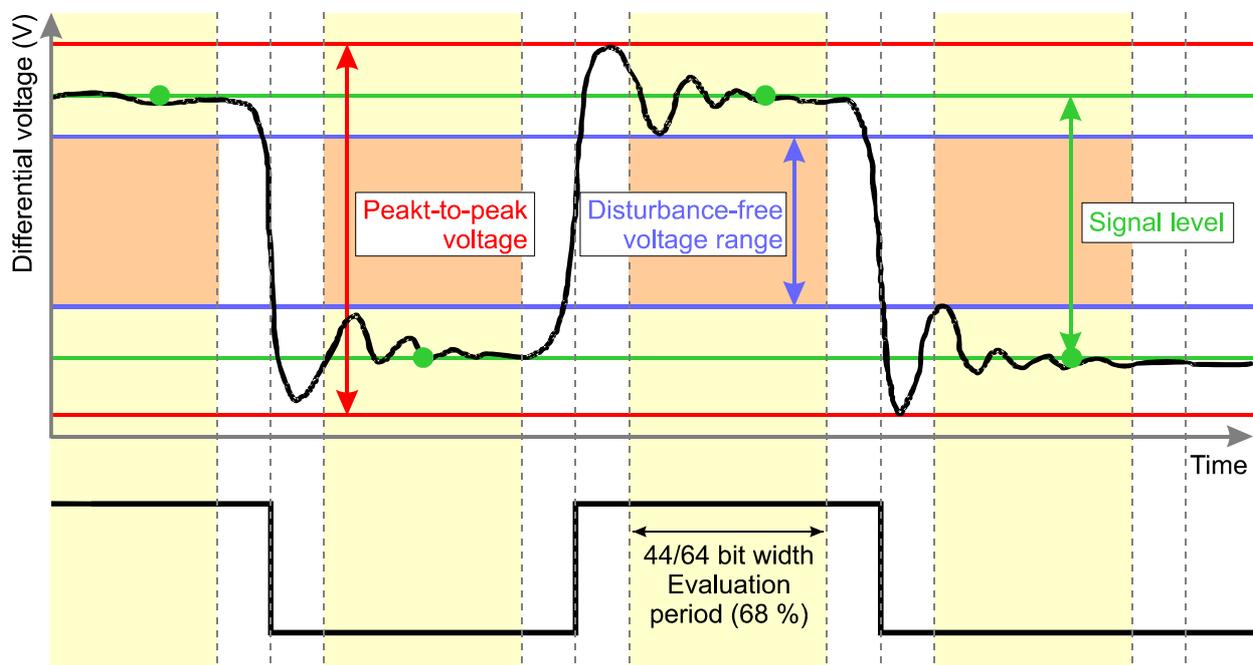
Figure 2: Definition of disturbance-free voltage range, peak-to-peak voltage and signal level

3.2.1.1 Enhanced measurement of the Disturbance-free voltage range

By using the existing process to measure the disturbance-free voltage range, sometimes drops in recessive bits could not be identified securely. Thus, the CANtouch firmware version v1.80 and the CAN-Bus Tester 2 PC software v4.4.0.0 and newer versions of them offer an enhanced measurement process by default. The manufacturer highly recommends to use this enhanced process for new measurements. As the disturbance-free voltage range also influences the calculation of the quality level, this value changes as well.

The old process is further available in Legacy Mode for compatibility intentions with existing measurements. That old process can be activated via Menu → Tools → Settings → Default → Legacy mode.

3.2.2 Edge steepness

To evaluate the transmission properties of the bus cabling and of the individual CAN bus stations completely, in addition to the disturbance-free voltage range, the edges must also be studied; shallow edges can also prevent the correct decoding of the transmission signal.

The CBT2 determines the edge steepness for rising and falling edges separately. To this end, two thresholds are set at 10% and 90% of the signal level determined (determined differential voltage at 42/64 = 2/3 = 66%, see Figure 2). The time required by the difference signal to change between these voltage threshold values is measured both for falling and rising edges. The rise and fall times are determined with a resolution of 1/64 of the baud rate used and displayed as a value between 0/64 and 64/64. This value always specifies the slowest rising and falling edge of the measured frame. A measured value of 0/64 means that the level change takes place in less than 1/64 of the bit width.

3.2.3 General quality level

The quality level is a generally valid expression of the signal quality on the bus. It represents the most important physical properties of the bus and summarizes these in a single value. The quality level is specified as a percentage value. The value range is 0...100%.

The value is determined from the following three components important for the signal quality:

- Edge steepness
  The edge steepness is measured as x/64. A steepness of 0/64 represents an ideal edge steepness and is valued as 100%. The worst flank is defined as 32/64 and equates to 0%.

$$Edge\,steepness\,[\%] \;=\; \frac{32-x}{32}\cdot 100\,\% \quad \rightarrow \quad x=0\ldots 32$$

- Disturbance-free voltage range
  A disturbance-free voltage range of 1.0 V is defined as 0% – a value of 2.2 V as 100%.

$$Disturbance-free\,voltage\,range\,[\%] \;=\; \frac{U_{disturb}-1.0\,V}{2.2\,V-1.0\,V}\cdot 100\,\% \quad \rightarrow \quad U_{disturb}=1.0\,V\ldots 2.2\,V$$

- Reflection
  Reflection is the relationship of the disturbance-free voltage range to the peak-to-peak voltage. If

the peak-to-peak voltage is identical to the disturbance-free voltage range, this is the ideal case and represents 100%. If the peak-to-peak voltage is twice the value of the disturbance-free voltage range, this is defined as 0%..

$$Reflection[\%] \ = \ (2 \ - \ \frac{U_{SS}}{U_{disturb}}) \cdot 100\% \quad \rightarrow \quad U_{SS}/U_{disturb} = 0.0\,V\,...\,3.0\,V$$

All three components contribute equally to the calculation of the quality level.

$$Quality\,level[\%] \ = \ \frac{Edge\,steepness[\%]}{3} \ + \ \frac{Dist.-free\,voltage\,range[\%]}{3} \ + \ \frac{Reflecions[\%]}{3}$$

3.2.4 Oscilloscope display with frame analysis

To evaluate signal transitions and for the measuring of reflections, the CBT2 records the signal waveform of the message frame and presents it in the oscilloscope display of the CBT2 application software. Sampling is performed at 64 times the set baud rate over a total of 160 bits (64 x 160 = 10,240 points). The trigger point for the recording always lies on the first edge of the relevant message frame with an advance of 10 bits. The trigger point can be set in the application software.

3.3 Online monitoring functions

The online monitoring functions are always active, independent of any measurements started in the individual views.

3.3.1 Bus status

The bus status provides a quick overview of the status of your CAN bus plant. A cyclic measurement over one second indicates whether or not data traffic (level change) is present and whether or not the CBT2 is connected correctly to the bus. If the plant is stopped (no data traffic), the idle level of the bus is measured and evaluated. If this value lies in an impermissible range, this will be indicated. Conclusions regarding errors in the bus cabling can be drawn from the value of this difference voltage. A precise description of the individual states is to be found in Section 4.4.3.1 „Bus status".

3.3.2 Bus traffic load

Not only configuration problems, but also diagnostic and alarm messages, as well as poor transmission properties and the resulting sporadic frame repetitions can extend the bus traffic load. Problems of this kind can be avoided by measuring the bus traffic load at regular intervals and saving the measured minimum and maximum values.

To ensure that this measurement functions correctly, the baud rate of the CAN bus segment must merely be set via the CBT2 application software and the CBT2 connected to the plant. The device then determines the bus traffic load cyclically over durations of one second each.

3.3.3 Error frames

Error frames belong to the error management functionality implemented in the data link layer in all CAN controllers. They permit detection of the following error types:

- Bit errors
- Bit stuffing errors
- CRC errors
- Format errors
- Acknowledgment errors

Each error which is detected by the error management is notified to all other bus stations by way of an error frame. This is achieved with a deliberate coding violation. All CAN controllers then discard this telegram destroyed by the error-frame and the sending CAN controller repeats this message again.

The counter for error frames - like the bus traffic load, is a real-time monitoring function. The background to this measurement is a protocol check of all frames transferred on the bus. If an active or passive error frame is detected, the corresponding counter is incremented. As a rule, the count of this display should always show "0". If sporadic, or even frequent errors occur, this is generally attributable to problems with the physical bus characteristics and the corresponding transmission problems.

The error frame counters of the CBT2 count up to a maximum of 1,000,000. The counters will only work correctly, however, if the correct baud rate has been set for the CAN bus segments via the CBT2 application software. If this is not the case, the frame detection will not function correctly. Subsequently, data traffic of any kind on the bus may lead to incrementing of the error frame counter.

4 The CBT2 Application Software

4.1 System requirements

To ensure the correct installation of the CBT2 application software, your PC or notebook should meet the following minimum requirements and possess one of the operating systems listed below:

Hardware:

- Processor: at least 2,0 GHz (2,4 Ghz dual core recommended)
- at least 512 MB RAM (1 GB recommended)
- Graphics card with 24-bit color depth (32-bit recommended)
- Resolution: 1,024x768 pixels or higher
- CD/DVD ROM drive
- free USB port

Supported operating systems:[2]:

- Microsoft Windows® XP
- Microsoft Windows® Server 2003
- Microsoft Windows® Vista (32 Bit and 64 Bit)
- Microsoft Windows® 7 (32 Bit and 64 Bit)

4.2 Installing the software

The PC software is available in German and English and is supplied on CD. The installation sets up the CBT2 application software on your system and installs the USB driver required by the device. To this end, perform the following steps:

1. Insert the CD into the appropriate drive of your PC.
2. The installation starts automatically[3].
3. Follow the instructions of the setup program.

Note:

To install the USB driver, you must possess administrator rights.

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2 Microsoft and Windows® are registered trade marks of Microsoft Corporation in the USA and in other countries.

3 If the installation does not start automatically, start the setup program either with "START" → "Run..." → "{drive letter of your CD drive}:*Setup.exe*" → "*OK*" or else directly with "{drive letter of your CD drive}:*Setup.exe*"

   If you do not possess administrator rights, you will be asked to enter the administrator password.

4.3 General notes on operation

4.3.1 Help

When designing the CBT2 application software, special attention was devoted to a clear structure and a self-explaining graphical user interface. All elements of the user interface display detailed explanations when the mouse pointer is moved over a control element ("tool tip").

The manual is also supplied in electronic form and can be called up both via the help function and with the F1 key.

4.3.2 Data saving

All measurement, protocol and export data set using the CBT2 application software and determined via the CBT2 device at the CAN bus plant, can be stored in a document with the file extension ".cbt2". The document can be opened either by double-clicking on the file in the Windows® Explorer or by dragging the file to the program (drag & drop).

4.4 Program structure

The graphical user interface of the CBT2 application software is divided into various areas (Figure 3).
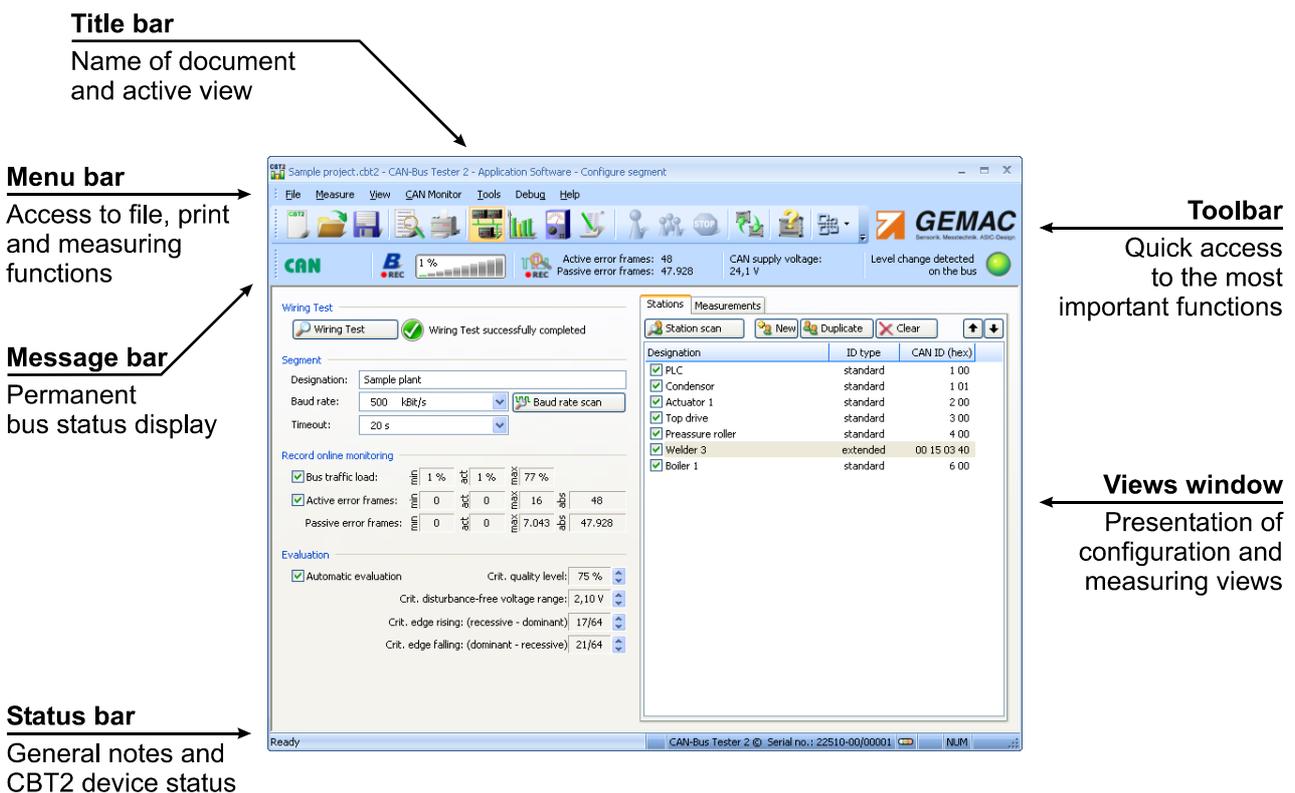
Figure 3: Structure of the CBT2 application software

4.4.1 Menu bar

The menu bar contains the main menus "File", "*Measure*", "*View*", "*Protocol Monitor*", "*Tools*" and "*Help*". Use the "*File*" menu to open, save, export and print CBT2 documents. The "*Measure*" menu provides the functions required to control measuring processes ("Start" and "Stop"). Use the "*View*" menu to switch be-

tween the individual measuring views. The menu function "*Protocol Monitor*" starts the log function for trans-mitted and received CAN/CANopen messages. The settings dialog can be found in the "*Tools*" menu; it can be used to configure the CBT2 application software and the CBT2 itself. The last menu item "*Help*" comprises the electronic manual, as well as program and device information.

4.4.2 Toolbar

For user-friendly operation and switching between the measuring tasks, a toolbar has been implemented in the CBT2 application software; this can be found in the upper part of the program window (Fehler: Referenz nicht gefunden). The toolbar provides quick access to the most important menu functions.

Figure 4: Toolbar

Opens a new document (Ctrl + N)

Opens an existing CBT2 document (Ctrl + O)

Saves the active CBT2 document either with its current name or - if the document has not been given a name - with a new name (Ctrl + S)

Shows how the active document will appear when printed (Print Preview)

Prints the active document (Ctrl + P)

Switches to the "*Configure segment*" view (Alt + 1)

Switches to the "*Measure All Stations*" view (Alt + 2)

Switches to the "*Measure One Station*" view (Alt + 3)

Switches to the "*Measure Online Trigger*" view (Alt + 4)

Starts a single measurement (F5)

Starts a continuous measurement (F6)

Green: Ends the measuring process after completion of a single measurement (F7)

Red: Ends the measuring process immediately (F8)

Opens a dialog box where you can select the CAN-Bus Tester 2 to be used (if more than one CAN-Bus Tester 2 is connected to your PC)

Opens the electronic manual. Make sure that a PDF display program is installed on your system, such as Adobe® Reader® (F1).

Displays program and device information and can be used to update the CBT2 firmware and FPGA configuration.

Changes the design of the graphical user interface.

4.4.3 Message bar

The message bar can be found directly beneath the toolbar and is always visible. It informs you continuously on the current status of the bus and on continuously running monitoring functions. Figure 5 provides a screen-shot of the message bar and its elements.
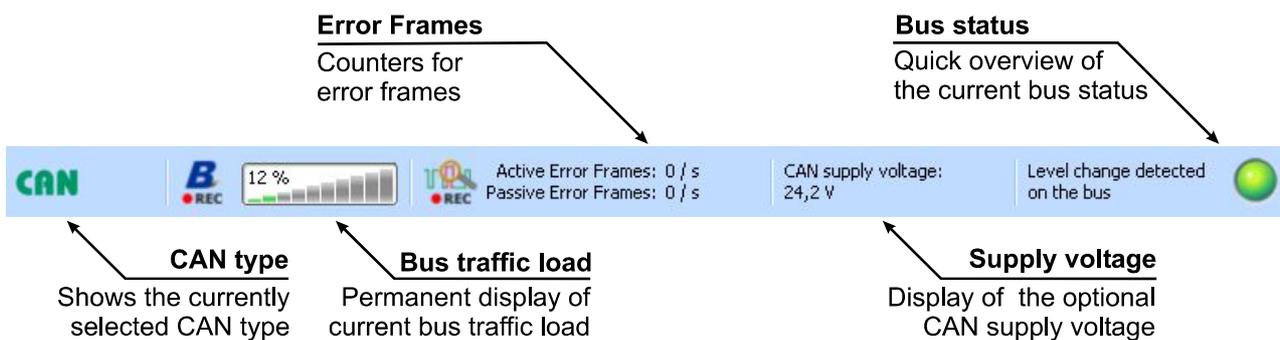
Figure 5: Message bar

4.4.3.1 Bus status

The bus status display comprises multicolor LED graphics and a description text. The LED changes its color depending on the bus status. For a detailed description of the bus status measurement, please refer to Section 3.3.1 „Bus status". The following states can occur:

LED = gray: CAN-Bus Tester 2 not connected to power supply and/or PC, or differential voltage in impermissible range 0.5 V ... 0.9 V.

LED = yellow: Bus static (no level change detected on the bus within the measuring time of one second); difference voltage less than 0.5 V, bus idle)

LED = red: Bus static (no level change detected on the bus within the measuring time of one second); difference voltage greater than 0.9 V)

LED = green: Level change detected on the bus

4.4.3.2 Error frame counter

The error frame counter is an online bus monitor. The CBT2 detects all active or passive error frames occurring on the connected CAN bus (for a detailed description of error frames, see Section 3.3.3 "Error frames"). The maximum count for error frames is 1,000,000. If this number is exceeded, ">1,000,000" is displayed. A double-click of the mouse on the display will reset this value to zero for both counters. The display of the error frames can be changed from maximum count to per second display by clicking with the right button of the mouse. Another right click of the mouse resets the display to maximum count. The related tooltip displays the values of both display options.

The values of the error frame counters can be recorded in a CBT2 document, like all other measurement data. The recording can be started or stopped by clicking with the left mouse button on the error frame icon or by activating the option "*Record online monitoring*" in the "*Configure Segment*" view. Any changing of the error frame counters from the time of activation is thus saved in the document and can later be displayed and printed in the test report. The "REC" icon indicates whether the recording is currently running ●REC or not ●REC.

It should be taken into account that the error frame counters are reset automatically after each change or after execution of the automatic baud rate detection. For correct frame detection and thus error analysis, it is imperative that the baud rate is set correctly; otherwise, traffic of any kind on the bus may be detected as an error.

4.4.3.3 Bus traffic load

The determination of the bus traffic load - like the error frame counters - constitutes an online bus monitoring function. As already described in detail in Section 3.3.2 "Bus traffic load", the bus traffic load is measured and updated constantly at intervals of one second.

The data of the bus traffic load display can also be recorded in a CBT2 document. Clicking with the left mouse button on the bus traffic load icon or activating the "*Record bus traffic load*" option in the "*Configure Segment*" view will start recording of the measurement data. The "REC" icon indicates whether the recording is currently running ●REC or not ●REC.

It should be taken into account that - as for the error frame counters - changing the baud rate and execution of the automatic baud rate detection results in a reset of the bus traffic load. For correct displaying of the bus traffic load, the baud rate must be set correctly.

4.4.3.4 CAN supply voltage

The supply voltage which is present optionally in the case of CAN/CANopen/SAE J1939 or always in the case of DeviceNet is measured and displayed cyclically.

4.4.4   Status bar

The status bar can be found at the bottom of the CBT2 application software window (Figure 6).

Ready | T | CAN-Bus Tester 2 © Serial no.: 22515-00/01014 | NUM
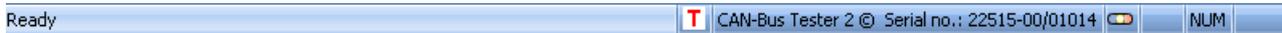
Figure 6: Status bar

When you navigate through the menus with the mouse pointer or the direction keys , the left area of the status bar describes the functions of the entries in the menu. This area also displays appropriate descriptions regarding the effects of the buttons on the toolbar if you move the mouse pointer over the buttons.

The right-hand area contains the trigger status icon, provides information regarding the CAN-Bus Tester 2 connected, and keyboard information. The trigger icon is always lit when a trigger pulse was initiated at the hardware trigger output. If a CAN-Bus Tester 2 is connected and is in use, its serial number is displayed.

4.5 Selecting the bus system (CAN / CANopen / DeviceNet / SAE J1939)

During a measurement, the CBT2 must detect message frames of the CAN bus station concerned, in order to be able to evaluate its physical bus signal. The assignment of the transmitted signal to a station is determined by the ID contained in each CAN bus message frame. With the settings CANopen, DeviceNet and SAE J1939, the Node ID, MAC ID or Source address is decoded from the CAN ID of the message frame and used for assignment of the station. As soon as this ID or Source address is detected, and if it is identical to that of the station to be measured, the frame concerned is physically measured. Only the frames transmitted from the stations to measure will be consulted for the evaluation of the bus physics and for the user scan – RTR frames will be ignored.

Figure 7: Bus system selection

The bus system is selected by creating a new document using the menu "*File*" → „*New...*" of the CBT2 application software (Figure 7 refers).

License note:

If no device is connected, all bus systems will be displayed and can be selected. If the CAN-Bus Tester 2 is connected, the bus systems supported by the device will be marked (see Section 6 „License Management"). Only those can be measured by the connected device. A creation or evaluation of documents with bus systems not supported by the connected tester is still possible.

4.6 „Configure segment" view

The „Configure segment" view is displayed directly after starting the CBT2 application software. Here you can enter the basic settings for measuring. Figure 8 shows a screen-shot.

4.6.1 Segment

If your CAN bus plant comprises several segments (bus segments separated by a repeater), you can optionally enter a name for the segment (max. 30 characters) in the field "*Designation*" for differentiation. The data transfer rate you wish to use for the CAN bus segment to be measured can be set under "*Baud rate*". You can also use the "Baud rate scan" function to let the CBT2 determine the baud rate automatically. If no message frame from the relevant station is detected within the time set under "*Timeout*", this time must be increased.

Figure 8: „Configure segment" view

4.6.2 Wiring test

With the wiring test, it is possible to determine line short-circuits, line breaks, the bus termination, the loop resistances of the CAN line and the CAN power supply line, and the overall line length. To ensure correct bus cabling, it is recommended to perform the wiring test at the beginning of any plant measurements.

The requirements for this measurement are:

- CBT2 operated on the supplied power pack (not via the plant CAN bus)
- CBT2 connected to the PC and to the plant CAN bus

- All bus stations removed / no bus traffic (bus status LED = yellow)
- CAN supply voltage display: approx. 0.0 V
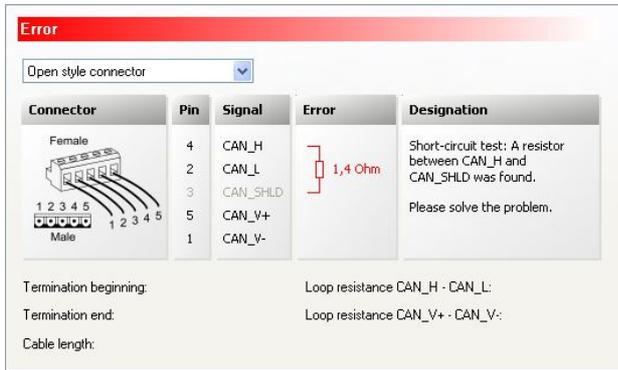
Figure 9: Wiring Test - Error
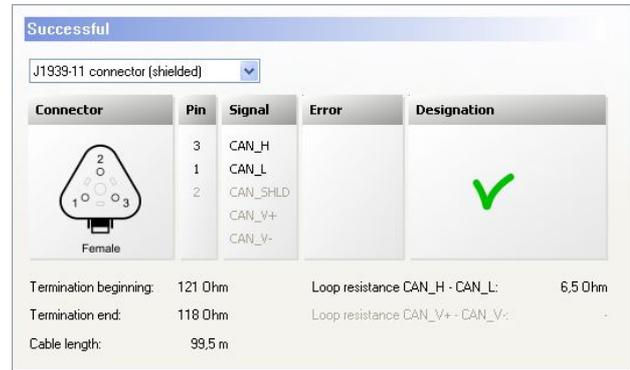
Figure 10: Wiring Test - Successful

The wiring test is performed as a sequence of four steps. The test requires certain interactions from the user, such as activation/deactivation of the terminators and connecting of a shorting plug. A wizard guides the user through the process.

4.6.3 Baud rate scan

The CBT2 can determine the baud rate for a segment automatically provided that the CAN bus plant is functioning correctly (data traffic present, bus status LED = green). Click on "Baud rate scan"; a dialog box is opened, displaying the baud rate detected. This can be confirmed and accepted by clicking on the "OK" button.

Note:
If the baud rate is changed, the error frame counter and the bus status display are reset. The protocol monitor is deactivated.

4.6.4 Station scan

The Station scan determines automatically, depending on the bus system selected, all transmitting stations or IDs transmitted on the bus and enters them in the List of stations.

4.6.5 Recording the online monitoring

The measured values "*Error frames*" and "*Bus traffic load*" displayed in the message bar can be recorded if necessary and also saved in the CBT2 document. To start recording, click with the left mouse button either on the option or on the appropriate icon in the message bar. The current measurement values are displayed in the text fields. While the recording is running, the ●REC icon is displayed in the message bar.

When using the recording functions, please note that the stored values will be lost after stopping and restarting the recording process and are then overwritten by the new values. For this reason, when opening a CBT2 document, the recording is at first always deactivated.

If the error frame counters or the bus traffic load are reset when recording (double-click on "*Error frames*" or "*Bus traffic load*" in the status bar), this will also have an effect on the recording values; they will be reset. The recording functions can be used independently of any other measurements performed on the CBT2.

4.6.6 Evaluation

When evaluating the measurement data, you are assisted by the CBT2 application software, which is able to provide for automatic evaluation of the results. This function is activated/deactivated via "*Automatic evaluation*". For the evaluation, the following limit values must be set and will be stored in the current document:

- Critical quality level (30 ... 90%; critical measured value if not reached)
- Critical disturbance-free voltage range (1.0 ... 3.0 V; critical measured value if not reached)
- Critical rising edge (recessive - dominant) (1/64 ... 48/64, critical measured value if exceeded)
- Critical falling edge (dominant - recessive) (1/64 ... 48/64, critical measured value if exceeded)

When the evaluation function is activated, the measured values are evaluated against the set critical limit values and - if necessary - highlighted. If any stations cannot be measured or if a timeout occurs, this information is also logged and displayed.

The set values serve as the thresholds for the online trigger measurement, irrespective of whether automatic evaluation is activated or deactivated.

4.6.7 List of stations

The List of stations contains all CAN bus stations determined using the Station scan function. Each station can be assigned a customized designation, and various settings can be made.

Subject to the selected bus system, the following columns are provided for the stations alongside the designation.

- CAN : ID type (standard / extended), CAN-ID (0x000...0x7FF / 0x00000000...0x1FFFFFFF)
- CANopen : Node ID (1...127)
- DeviceNet : MAC ID (0...63)
- SAE J1939 : Source address (0...253)

The checkbox to the left of each station designation displays whether or not the appropriate station is included in the measurements (☑ = „to be measured") or (☐ = „not to be measured"). To switch, either click with the mouse on the relevant icon, or use the context-sensitive menu (right mouse button) or the keyboard (spacebar).

To rename a station, either click on the "*Rename*" button, double-click on the cell, use the context-sensitive menu or the keyboard (F2 key). The other parameters in the list can be changed in the same way.

To detect any faulty adaptation on the bus more easily, it is recommended to arrange the stations according to their physical order sequence on the bus. The order can be changed manually using the and buttons [↑] and [↓] or by drag & drop. Click on the column header for automatic sorting in ascending or descending order of designation, ID type, CAN ID, Node ID, MAC ID or Source address.

4.6.8 List of Measurements

The List of Measurements be used to manage different measurements. Each measurement possesses a symbol for the measurement type, a measuring point designation, a time stamp and, at the bottom edge of the list, an individual description.

To rename a measuring point, either click on the "*Rename*" button, double-click on the cell, or use the context-sensitive menu or the keyboard (F2 key).

As with the List of stations, this list can also be sorted automatically in ascending or descending order by clicking on the corresponding column header. The default measurement is always placed at the top, irrespective of the sorting.

The measurement data for the default measurement are not saved in the document.

4.7 „Measurement All Stations" view

4.7.1 How to use

The „Measurement All Stations" view provides an overview of the signal conditions of all stations. The measured quality value is displayed clearly in a bar diagram for each station. Any minimum and maximum values are also marked graphically so that variations can be recognized easily. This view also displays minimum and maximum values for the quality level, together with a time stamp.

The measurement can be carried out both as a single measurement (each station is measured only once) and as a continuous measurement. Figure 11 shows a screen-shot of this view.

4.7.2 Setting and Measuring

The requirements for this measurement are:

- The CBT2 is connected both to a PC and to the CAN bus plant (bus status LED = green or yellow)
- The correct baud rate is selected.
- At least one station exists in the List of stations and is marked as "*to be measured*".

Figure 11: „Measurement All Stations" view

After switching to the „Measurement All Stations" view ("*View*" menu or toolbar), you can control the measurement using the following icons or menu functions ("*Measure*" menu):

Starts a single measurement (F5)

All stations marked in the List of stations as „*to be measured* (☑) are measured once. The measurement ends automatically once the whole segment has been measured once.

Starts a continuous measurement (F6)

All stations marked in the List of stations as „*to be measured*" (☑) are measured cyclically. The measurement can also be ended with "*Stop*".

End measurement (F7)

The measurement is carried out up to the last station to be measured and then ended.

Cancel measurement (F8)

Clicking on this button ends the measurement immediately.

While the measurement is running, an arrow symbol is displayed beneath the station currently being measured. If no message frame from the station concerned is detected within the set timeout time (see Section 4.6 „Configure segment" view) this is indicated with "Timeout". In this case, check the status of the station in question or increase the timeout time.

4.7.3 Evaluation

The measured stations are displayed in the diagram as a bar. If there are more than 32 stations, you can navigate using the scrollbar. Use the "*View*" option to view the measured data for the desired station and to display a summary for all stations. To select a station, highlight the appropriate bar in the diagram. Its designation and measured data are displayed in a separate table. The measurement data record of a station comprises the quality level and the minimum and maximum values of the last continuous measurement, together with the corresponding time stamps.

With the automatic evaluation activated („Configure segment" view), a red line highlighting the critical quality level is shown in the bar diagram. This bar is yellow if the minimum value of a station is below this limit. If the value is above the limit, the bar is displayed in green.

In addition, it is possible to compare the current measurement with a previously recorded measurement. To do so, activate the "Compare with existing measurement" option and choose the relevant measurement. The corresponding measured values are then displayed to the left of the bar for the current measurement (see also Section 4.10 „Working with measurements").

4.8 „Measurement One Station" view

4.8.1 How to use

This measurement is intended to study one single station more specifically. It displays the quality level, the disturbance-free voltage range, the worst rising and falling edges, the complete signal waveform and the last detected message frame for the selected station. Figure 12 shows a screen-shot of this view.

This measurement simplifies the station-related display and evaluation of the data sent along the CAN bus through the use of an oscilloscope, since triggering is only coupled to exactly one station address. Section 2.3.4 "Connecting to the digital storage oscilloscope" describes in detail, how the CBT2 can be used in conjunction with an oscilloscope.

4.8.2 Setting and measuring

The requirements for this measurement are:

- The CBT2 is connected both to a PC and to the CAN bus plant (bus status LED = green or yellow)
- The correct baud rate is selected.
- At least one station exists in the List of stations and is marked as „to be measured"
- The station to be measured must be selected

Measurement Selection
Selection of an existing measurement

Saving
Saving of new measurement data

Station
Selection of the station to be measured

Dist.-free volt. range
Display of the measured disturbance-free voltage range and its fluctuation

Oscilloscope display
Signal waveform, including decoding acc. to protocol (logical and physical view)

Measured values
Minimum, maximum and current values, with time stamp

Edges
Display of edge steepness (rising and falling)

Figure 12: „Measurement One Station" view

After switching to the „Measurement One Station" view ("*View*" menu or toolbar), you can control the measurement using the following icons or menu functions ("*Measure*" menu):

Starts a single measurement (F5)

Station selected: The station to be measured is measured once.

No station selected: All stations will be measured automatically in succession.

Starts a continuous measurement (F6)

Station selected: The station to be measured is measured cyclically.

No station selected: All stations will automatically be cyclically measured in succession.

The measurement can also be ended with "*Stop*".

Cancel measurement (F8)

Clicking on this button ends the measurement immediately.

Once a station is selected the current measurement data is displayed whilst the measurement is in progress. The current measurement data are displayed while the measurement is running. The CBT2 outputs a trigger pulse at its BNC socket whenever a message frame of the relevant station is detected ("**TRIGGER**" LED lights green). With this trigger signal, the transmitted frame can be displayed in true time on an oscilloscope, as described in Section 2.3.4 "Connecting to the digital storage oscilloscope".

If no station is selected all stations listed will be measured in succession. A live display of the measurement data and the trigger output for the storage oscilloscope is not available. In this case, a dialog window informs about the progress of the current measurement.

If no message frame from the station concerned is detected within the set timeout time (see Section 4.6 „Configure segment" view) this is indicated with "*Timeout*". In this case, check the status of the station or extend the timeout time (see Section 4.6 „Configure segment" view).

4.8.3 Evaluation

During and after the measurement of a station, this view displays the current, maximum and minimum measured valued for the quality level, together with the corresponding time stamps and the disturbance-free voltage range. The slowest rising and falling edges are displayed as multiples of 1/64 of the bit width.

With automatic evaluation activated („Configure segment" view), the instrument indicates the critical disturbance-free voltage range by way of a red arrow. The relevant numerical value is displayed in yellow, symbolizing that the smallest measured disturbance-free voltage range lies below the set limit value. If the critical edge value is exceeded, the edge diagram is displayed in yellow. If the value is below the limit, the edge diagram is displayed in green.

The oscilloscope display can be switched between logical and physical representation both during and after the measurement of a station. The logical representation shows the analog signal of the measured frame together with an overlaid decoding of the CAN protocol. Use the "Zoom" function ("+" and "-" buttons) to enlarge or reduce the time section. To navigate within a zoomed-out section, use the scrollbar. The left mouse button can be used to change the trigger time of the frame (start bit). If CANopen is the selected bus system, the Node ID is displayed when the mouse pointer is placed over the ID; for DeviceNet, the MAC ID and for SAE J1939 the Source address is displayed.

The physical representation simplifies evaluation of any signal dips and reflections. From the height of the dip, it is possible to infer the changes in the characteristic wave resistance of the cable. The length and the position of the reflections indicate the distance to the point of interference. In this display, it is possible to draw up a range with the right mouse button, permitting simple calculation of the reflection heights and lengths, and thus of distances. The signal runtime is converted into a distance specification automatically.

For the calculations, a mean bus cable runtime constant of 4.5 ns/m is assumed for CAN/CANopen/SAE J1939 or 4.3 ns/m for DeviceNet.

4.9 „Measurement Online Trigger" view

4.9.1   How to use

The online trigger measurement serves for long-term analysis of the bus system over several days/weeks. In this way, both sporadic bus disturbances (external EMC influences) and a slowly deteriorating signal quality (e.g. due to liquid in the connector) can be detected. For this measurement, **all** message frames on the bus (irrespective of the stations in the List of stations) are subject of the online physical and logical evaluation, and any deviations from a predefined threshold value are recorded.

The online trigger can recognize the following trigger events:

- ■ Logical events/ errors
    - ■ Active error frames
    - ■ Passive error frames
    - ■ Overload frames
    - ■ Acknowledge errors
- ■ Physical errors
    - ■ Failure to reach a critical quality level
    - ■ Failure to reach a critical disturbance-free voltage range
    - ■ Exceeding of a critical edge (rising)
    - ■ Exceeding of a critical edge (falling)

Each of these trigger events possesses a separate channel, leading to a trigger when activated. All are displayed, irrespective of the activating of a trigger event. For the duration of the activated event, the "**TRIG-GER**" LED lights red. Figure 13 shows a screen-shot of this view.
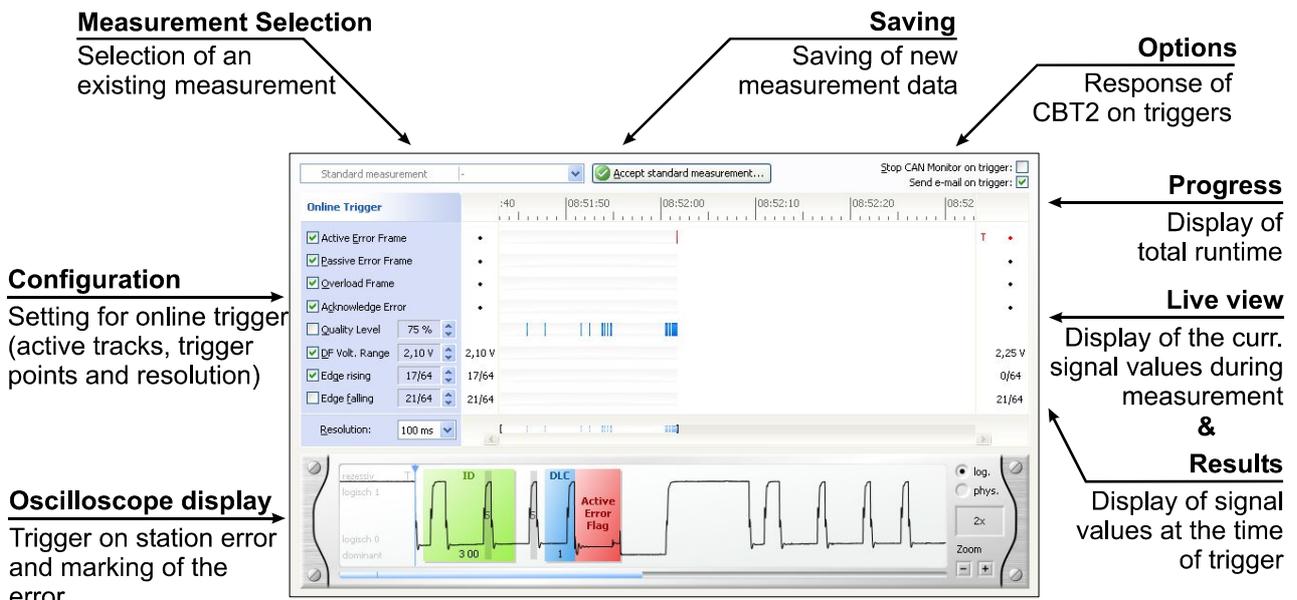
Figure 13: „Measurement Online Trigger" view

4.9.2 Setting and measuring

The requirements for this measurement are:

- The CBT2 is connected both to a PC and to the CAN bus plant (bus status LED = green or yellow)
- The correct baud rate is selected.

After switching to the „Measurement Online Trigger" view ("*View*" menu or toolbar), you can control the measurement using the following icons or menu functions ("*Measure*" menu):

Starts a single measurement (F5)

Starts a single online trigger measurement. Measuring stops automatically when the first error event occurs.

Starts a continuous measurement (F6)

Starts a continuous online trigger measurement. Measuring does **not** stop when error events occur. The error events are displayed graphically in the corresponding channel.

End measurement (F7)

The continuous online trigger measurement is switched to single measurement, so that measuring stops automatically when the next error event occurs.

Cancel measurement (F8)

Clicking on this button ends the measurement immediately.

The time axis resolution for the recording of the trigger events is set in the "Resolution" selection box. The shorter the selected time, the greater the amount of measurement data to be assessed. Within the set time (time slice), each trigger event is recorded in its corresponding channel. Several trigger events (e.g. two faulty frames) within one time slice can no longer be distinguished. In this case, the resolution must be increased. It is not meaningful to set the resolution to a time less than the time required for a message frame at the set baud rate. Each time slice is represented in the display with the width of one pixel.

In Single Measurement the CAN controller of the protocol monitor will automatically be stopped when a trigger event occurs if the option "Stop CAN controller on trigger" is activated. The message frame in the oscilloscope display then corresponds to the last entry in the receive window of the protocol monitor. The frames preceding the trigger can thus be analyzed.

The "Send e-mail on trigger" option can be selected if the necessary configuration of the e-mail client has been performed in the Settings dialog (Section 4.14.3 : „E-mail notification"). When the option is activated, an e-mail with a description of the trigger event and a corresponding screen-shot is sent to the e-mail recipient. Successful sending of the e-mail is indicated in a message box.

When a trigger occurs, a trigger pulse is made available at the BNC socket. The "**TRIGGER**" LED then lights green.

4.9.3 Evaluation

The measured values acquired up to this point can be evaluated even while the measurement is still running. A time slice can be marked with the left mouse button. A tool tip is also displayed with additional information about this time slice. The time is displayed above the recorded channels, and an overall channel be-

low the channels. This permits localization also of trigger events which lie outside the current screen area. To the left of the channels, the critical threshold set for the evaluation at the start time is displayed. Whilst the measurement is in progress, the current data of the individual channels is displayed on the right hand side. When a trigger occurs, the current value of the individual physical errors at the time of triggering can be seen. The channel in which the trigger occurred is marked with a **"T"**. It is possible for there to be several trigger events at one trigger time.

The oscilloscope display shows the message frame which produced the trigger. All setting and evaluation possibilities correspond to those for the oscilloscope display in the „Measurement One Station" view.

4.10 Working with measurements

Each measurement is initially made as a default measurement and is not saved in the document. This ensures that existing measurements in a document are not overwritten. Furthermore, comparison measurements can be performed quickly without altering the existing document.

The default measurement is saved with the "Accept Measurement" button in the individual views. When doing so, it is possible to either save the default measurement as a new measurement or overwrite the measurement data of an existing measurement.

Measurements can be managed conveniently in the measurement list of the „Configure segment" view (see Section 4.6.8 "List of Measurements").

4.10.1 Measuring at different points

When starting up and for troubleshooting on a CAN bus plant, it is generally recommended to perform measurements at different points of the bus cabling – at least at the two bus ends. To be able to compare these measurements conveniently, the CBT2 application software offers a function to manage different measurements. When a default measurement is accepted as a new measurement, the measuring point should be filled out in accordance with the point at which the CBT2 is connected to the plant. In the evaluation of the „Measurement All Stations" view, the measurements from different measuring points can then be overlaid for troubleshooting assessment.

4.10.2 Measuring at different times

Not only the measuring point, but especially the measuring time is interesting in the case of recurring plant measurements at specified maintenance intervals. When a default measurement is accepted as a new measurement, the time is automatically saved. In the evaluation of the „Measurement All Stations" view, the measurements at different measuring times can then be overlaid for assessment to detect deterioration over a longer period of time.

4.11   Printing a test record

After all measurements have been completed, a comprehensive test record can be printed via the CBT2 application software to document the correct functioning of a CAN bus plant or to show detected problems. The test record consists of individual data areas. Before printing or displaying the print preview, the contents of the data areas can be adapted individually for a selected measurement and station. To this end, the dialog box shown in Figure 14 is displayed each time you call a print preview or printing so that you can adapt the test record accordingly.

Use the „Print options" menu item to select the data areas to be displayed or left out of the test record. All settings you make in this dialog box are saved in the currently active document.
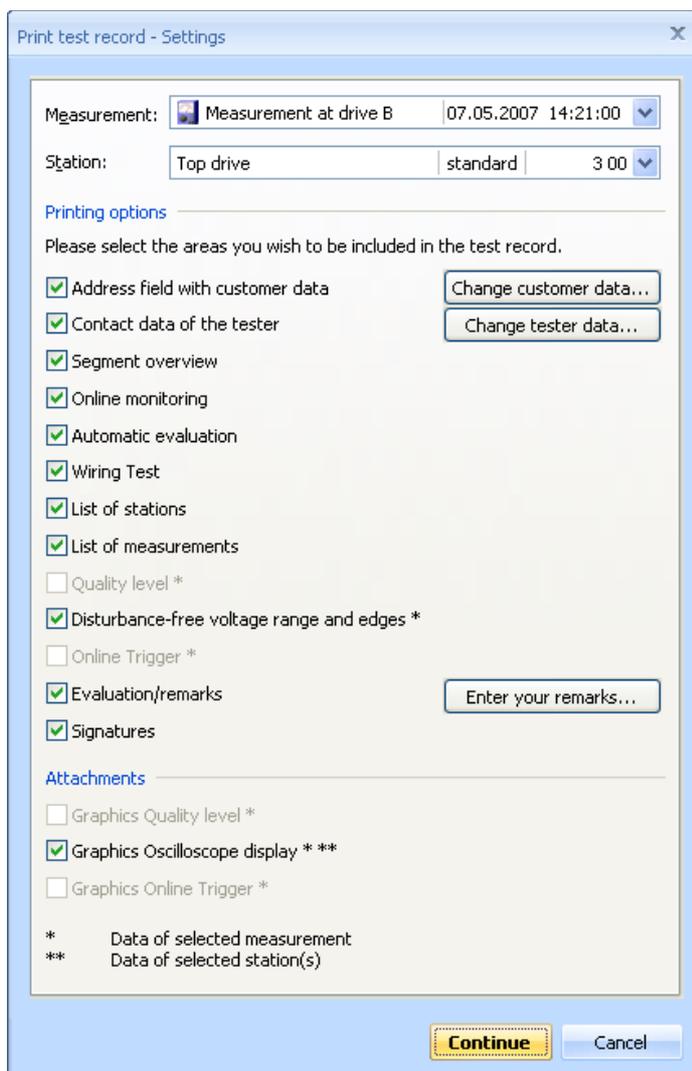
Figure 14: Test record settings

The areas "Address field (customer data)", "Contact data of the tester" and "Signatures" are intended specifically for the service and maintenance companies. The customer address can be entered under "Change customer data". Access to the contact data of the tester (= service and maintenance company) can be obtained under "Change tester data".

There are various data areas which can only be printed if you also possess measurement data for the selected measurement point (*) and/or station (**). If this is not the case, the relevant selection box is disabled.

Various graphics can be printed as an attachment to the test record. If no station is selected, the graphics of all listed stations will be printed automatically.

Note:
For reasons of formatting, the test record can only be printed in DIN A4 portrait format (or larger).

4.12 Exporting measuring data

4.12.1 CSV file

In addition to the option of measurement data output as a test record, the contents of a CBT2 document can also be specified as a CSV file. This file can be read using any standard spreadsheet program, enabling the measured data to be processed further.

If all measurements are completed, the export function can be called using the "*File*" → "*Export...*" menu. A settings dialog appears (Figure 15 refers) where measurements to be exported and required data areas are selected. The CSV data can be transferred to a spread sheet via the clipboard or saved in a file.
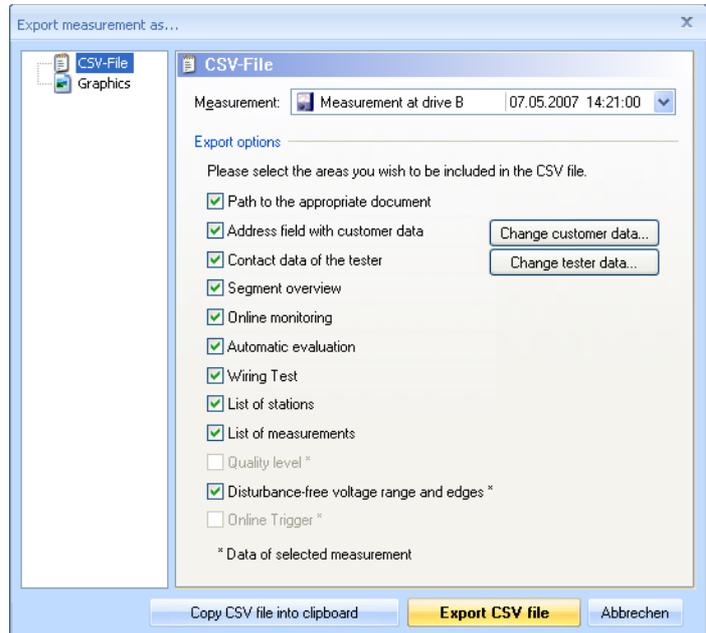
Figure 15: Export measurement - CSV file

When opening or importing the CSV file into a spreadsheet program, observe the following formatting settings to ensure that all columns, lines and data formats are imported correctly:

- Column delimiter: (the list separator set in the system, usually a semicolon)
- Line separation: Carriage Return + Line Feed (CRLF = 0x0D0A)
- Decimal delimiter: (the decimal delimiter set in the system, usually a dot)

4.12.2 Graphics

Use the "*File*" → "*Export...*" menu to export various graphical representations of measurement data as bitmap graphics (.bmp,.jpg and .png). The image data can be exchanged swiftly with other programs via the export to the clipboard. The measurement and the preferred picture area can be selected in the settings dialog. If „All stations" of „Measurement One station" is selected, the graphics of all stations will be saved in a chosen directory automatically. A preview allows easy selection of the measuring data to be exported (Figure 16 refers).
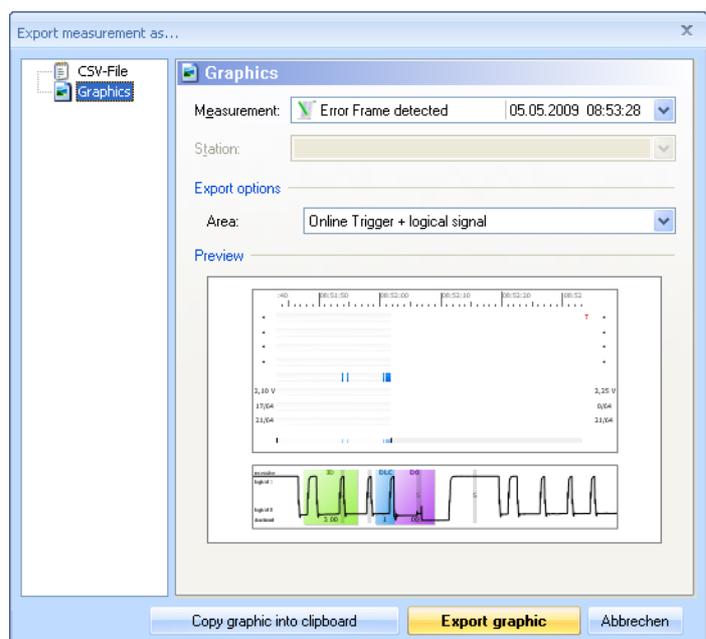
Figure 16: Export measurement - Graphics

4.13   Importing measuring data

The command "*Import*"→ "*CANobserver*" in the "*File*" menu imports measuring data recorded with CANobserver®[4] to the CBT2 application software. The CANobserver® is a diagnostic tool for the physical and logic long term surveillance of CAN bus plants and is designed as a stationary extension of the CAN-Bus Tester 2. It's functionality is equivalent to the track display implemented in the measurement "On-line Trigger".   Contrary to the CAN-Bus Tester 2, the CANobserver® is permanently integrated in the CAN network and continuously monitors the data transfer which is recorded automatically for up to 4 years without being connected to a pc. The CANobserver® allows the parametrization of the monitoring and the evaluation of the recorded data to be effected by using a web browser via the integrated web interface or by a SNMP inquiry via a control center.

All recorded data can be exported to a XML-file. The application will switch to the „Measurement Online Trigger" view when importing data. This view provides the same comfortable evaluation functions that are available during measurements using the CAN-Bus Tester 2.
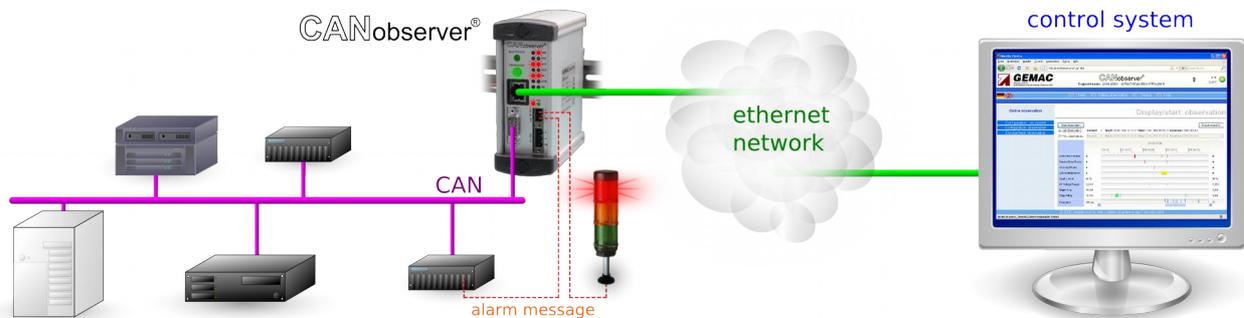
Figure 17: Application CANobserver®

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4   CANobserver® is a registered trademark of GEMAC – Gesellschaft für Mikroelektronikanwendung Chemnitz mbH

4.14   Settings

The "*Settings...*" command in the "*Tools*" menu opens a dialog box where you can adapt the program to your specific requirements. Here you can influence the behavior of the application software and of the CBT2 device. The settings in this dialog box will not be saved in the current document, but instead in the Windows® registry for the program.

4.14.1   General

Language	Changing the language between German and English. The switching of the language requires a restart of the software.
Display tool tips	If the mouse pointer is left over a particular screen element, e.g. a button, for a short time, the program displays a so-called "tool tip" with brief info about this element.
Display all warnings and messages again	The CBT2 application software displays warning and message dialogs in certain situations. A check box within these dialogs enables such messages to be skipped in the future (e.g. "*Do not display this message again*."). If you wish the messages to be displayed again, select this option.
Show bus system selection dialog at program start	Select this function to display the Bus system selection dialog each time the program is started. If this option is deactivated, the bus system **CAN** is selected as the default. The bus system selection dialog can still be called at any other time with "*File*" → "*New*".
Enable extended protocol view	Select this function to display a complete decoding of the CAN message in the oscilloscope display. If the option is deactivated, only ID, DLC, Data and CRC are displayed.
Show disturbance-free voltage range	Select this function to add a graphic representation of the measured disturbance-free voltage range to the oscilloscope display
Show peak-to-peak voltage	Select this function to add a graphic representation of the measured peak-to-peak voltage to the oscilloscope display
Show inactive tracks	Select this function to show deactivated tracks in the „Measurement Online Trigger" view. This can decline the clarity of the display in cases where there are many errors on the bus.
Show telegram traffic	Select this function to show telegram traffic in the track display of the „Measurement Online Trigger" view.
Activate trigger output on errors even during running continuous measurement	When activated the trigger impulse will be released even during a continuous measurement when an error occurs. Otherwise, only when the trigger occurs and the single measurement is stopping.
Enable legacy mode for disturbance-free voltage range	Activate this function for backward compatibility with existing measurements

4.14.2 Tester contact data

Use the CBT2 print function and the option of exporting the data to a CSV file to display the contact data of the plant tester. Use this tab to enter your contact data (optional).

4.14.3 E-mail notification

To enable e-mail notification in response to a trigger event in the „Measurement Online Trigger" view, the integrated e-mail client must be configured.

Server host name	Enter the address of the outgoing mail server. Example: *smtp.web.de* or a company SMTP server
Authenticate with user name and password	Select this function if the outgoing mail server requires authentication. In this case, enter your user name and password. The password is saved in encrypted form.
Address sender	Enter your own e-mail address. For the mail recipient, this address will be specified as the sender of the mail. Attention: Some e-mail servers check the validity of this address before forwarding the e-mail in question.
Address recipient	Enter the e-mail address of the person to whom the e-mail is to be sent.
Subject	This entry is optional. For the mail recipient, it will be displayed as the mail subject.
Send e-mail	Sends a test e-mail to check the configuration.

4.14.4 Bit timing

Use this menu to set the bit timing of the CAN controller for the selected baud rate. Adjustable are the number of BTL cycles[5] (tq), the sample point in percent and the resynchronization jump width (SJW). If you are using other than the recommended settings from the CiA, this is indicated by a warning sign in front of the corresponding baud rate in the dialog.

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5   The number of BTL cycles applies only to the CAN controller. The bit sampling for the physical measurements is always 64 times.

4.15 Protocol Monitor

The "Protocol Monitor" can be used to visualize CAN or CANopen messages online and to transmit CAN messages defined by the user.

The "Protocol Monitor" operates independently of the CBT2 measuring functions. Separate program windows are provided to transmit and receive CAN messages. The following functions are available in all protocol monitor windows.

Status LED on the CAN controller:

Green: The CAN controller is activated; transmit and receive are possible.

Yellow: The CAN controller has reached or exceeded its warning limit.

Red: The CAN controller has been turned off automatically (is in Bus OFF status).

Gray: The CAN controller is deactivated.

Starting/stopping the CAN controller, Stop/continue receiving:

	Start CAN Controller	Activates the CAN controller with the baud rate set in the CBT2 application software (F5).
	Stop CAN Controller	Deactivates the CAN controller (F6) (Automatic deactivation when scanning the baud rate and switching the baud rate in the CBT2 application software)
	Stop / Continue Receiving	Reception of frames in the receive modules can be paused and continued respectively. The CAN controller remains active.

4.15.1   Protocol Monitor: CAN Transmit

License note:

Transmitting of messages and sequences are only available if the corresponding software module is supported by the connected CAN-Bus Tester 2. (see Section 6 „License Management"). The software modules supported by the device are listed in the information dialog (menu: "*Help*"→ "*About CAN-Bus Tester 2*").

The module *"CAN Transmit"* can be called via the "*Protocol Monitor*" → "CAN *Transmit*" menu of the CBT2 application software. It serves to transmit CAN messages either once or cyclically. For this purpose, you can define your own CAN messages in a list.
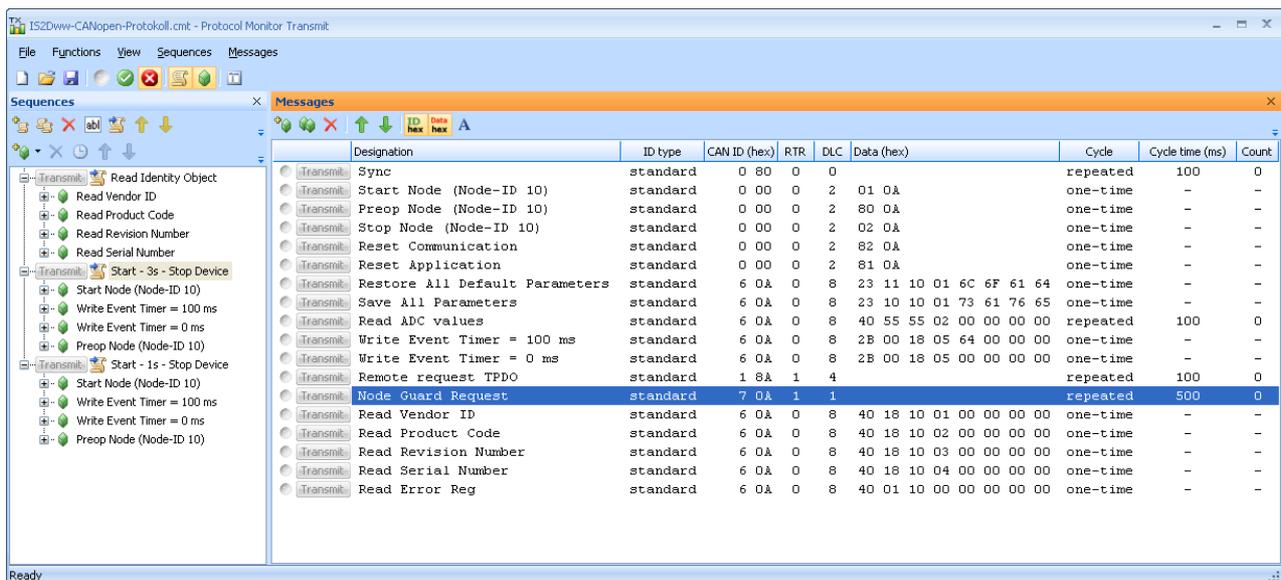
Figure 18: Module: CAN Transmit

4.15.1.1   Functions

The following functions are provided by the menu and by the toolbar of the "Protocol Monitor Transmit" menu:

	New	Opens a new "Protocol Monitor Transmit" document (Ctrl+N).
	Open...	Opens an existing "Protocol Monitor Transmit" document (Ctrl+O).
	Save	Saves the current "Protocol Monitor Transmit" document with its existing name or - if the document has not yet been given a name - with a new name (Ctrl+S).
	Show Sequence View	Shows the sequence view
	Show Message View	Shows the CAN message view
	Reset Window Layout	Reset the windows layout to its default values

4.15.1.2 View "Messages"

CAN messages can be created and configured in the View "Messages". In this view the CAN messages are transmitted once or repeatedly.

	Create Message	Creates a new CAN message at the current position (Ins).
	Duplicate Message	Duplicates a selected CAN message (Ctrl + Ins).
	Delete Message	Deletes the selected CAN message (Del).
	Message Move Up	Moves a selected CAN message in the list one place up (Shift+Arrow Up).
	Message Move Down	Moves a selected CAN message in the list one place down (Shift+Arrow Down).
	Switch ID display	enabled: display hexadecimal disabled: display decimal
	Switch data display	enabled: display hexadecimal disabled: display decimal
	Font...	Opens a dialog to setup the font in the view "Messages".

The following properties can be used to define a CAN message:

Cycle	single:	The CAN message is transmitted once.
	multiple:	The CAN message is transmitted cyclically with the set cycle time (10 ms ... 60,000 ms). Up to max. 10 CAN messages can be defined as "multiple".
Cycle time		Interval in ms with which a CAN message is transmitted repeatedly. If this option is selected, the cycle must be defined as "multiple".
ID type	standard:	CAN ID acc. to standard protocol, 11-bit (0x000...0x7FF)
	extended:	CAN ID acc. to extended protocol, 29-bit (0x00000000...0x1FFFFFFF)
CAN ID		Identifier of the CAN message to be transmitted
Name		Name of the CAN message. This name can be used by all other CAN messages with the same CAN ID.
Description		Additional description of a CAN message.
RTR		Definition of the frame type: 0: Data frame, 1: Remote frame
Data		Used to enter the data to be transmitted. The number of bytes entered is used for the data length code (DLC), irrespective of the selected frame type (RTR).

Selecting the "*Transmit*" button transmits the appropriate CAN message either once or repeatedly. Selecting the button once more deactivates the multiple transmission of a CAN message.

4.15.1.3   View "Sequences"

In the View "Sequences" the created CAN messages are grouped into sequences. This makes it possible to send multiple CAN messages with a defined time interval once or repeatedly.

	Create Sequence	Creates a new sequence at the current position (Ins).
	Duplicate Sequence	Duplicates a selected sequence (Ctrl+Ins).
	Delete Sequence	Deletes the selected sequence (Del).
	Rename Sequence	Renames the selected sequence (F2).
	Change Cycle (one-time/repeated)	Activates one-time or repeated transmission of the selected sequence. (F3).
	Sequence Move Up	Moves a selected sequence in the list one place up (Shift+Arrow Up).
	Sequence Move Down	Moves a selected sequence in the list one place down (Shift+Arrow Down).
	Insert Message	Inserts a CAN message into the selected sequence.
	Remove Message	Removes a selected CAN message from the sequence (Del).
	Change Waiting Time After Message	Changes the waiting time after the selected message (F4).
	Message Move Up	Moves a selected CAN message in the sequence one place up (Shift+Arrow Up).
	Message Move Down	Moves a selected CAN message in the sequence one place down (Shift+Arrow Down).

4.15.2 Protocol Monitor: Receive Modules

The protocol monitor modules "*CAN Receive*" and "*CANopen Receive*" can be called via the "*Protocol Monitor*" menu of the CBT2 application software.

4.15.2.1 Functions of both modules

The following functions are provided by the menu and the toolbar:

	New	Opens a "Protocol Monitor Receive" document (Ctrl+N).
	Open...	Opens an existing "Protocol Monitor Receive" document (Ctrl+O).
	Save	Saves the current "Protocol Monitor Receive" document with its existing name (Ctrl+S).
	Delete list	Deletes all received CAN messages from the list
	Filter	Sets a filter for the CAN messages to be received ("Hide/unhide CAN messages)
	Trigger	Activation of a trigger on the CAN-ID or data fields with adjustable amount of telegrams after trigger (F10)
	Scroll	Displays the CAN messages in the order in which they were received
	Overwrite	Displays the received CAN messages sorted by their CAN ID.
	Time stamp, relative	Displays the time stamp relative to the time stamp of the CAN message received previously
	Most recent	Shows the most recent CAN/CANopen message in the list.
	Font...	Opens a dialog to setup the font in the view "Messages".
	Search	Opens the "*Search*" dialog. Allows searching the ID- or the data field (Ctrl+F)
	Continue search	Searches for the next term specified by "*Search*" (F3)
	Search backwards	Searches for the previous term specified by "*Search*" (Shift+F3)

4.15.2.2   Filter

The "*Filter...*" command in the "*Settings*" dialog enables the configuration of a filter[6] for CAN messages. There are two lists for filtered and accepted identifiers. You can choose a complete identifier group by way of the masks or else perform a direct selection of the identifiers to be filtered.
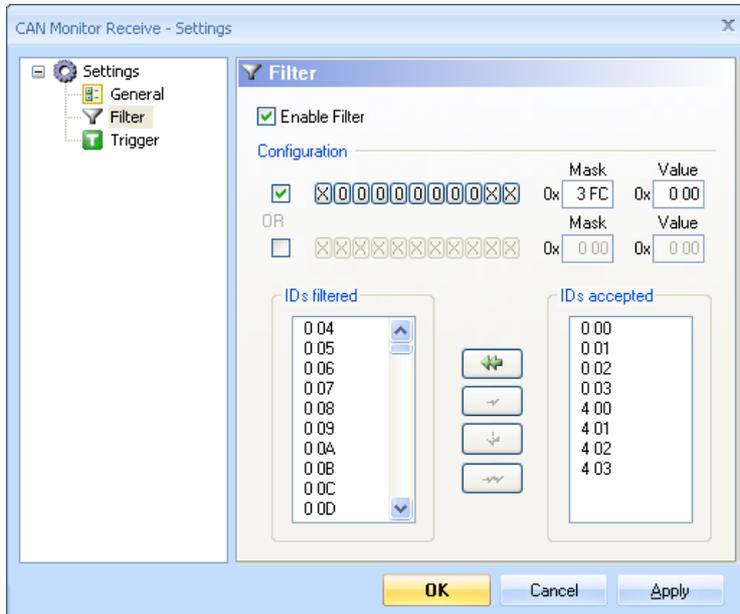
Figure 19: Filter options

A maximum of two OR'd masks is provided to select an identifier group. Each bit in the identifier masks can be assigned to one of the following values:

- ▪ X - Bit is not relevant
- ▪ 0 - Bit is relevant and must be "0"
- ▪ 1 - Bit is relevant and must be "1"

The selection can be performed either using the appropriate buttons or by entering the appropriate hexadecimal values for Mask and Value. The bit value "1" in the Mask field means that this bit is relevant, while bit value "0" means that this bit need not be used for filtering. In the Value field, you specify the bit value which the relevant bits in the Mask field must assume to be accepted by the filter.

For the direct selection, the relevant identifiers can be highlighted in the lists and moved between the groups of filtered or accepted IDs. Direct selection will deactivate the filtering of identifier groups.

---

6   The filter is available for 11 bit identifier only

4.15.2.3 Trigger

The command "*Trigger...*" can be found in the "*Settings*" dialog and allows the user to configure a trigger on CAN-IDs (standard or extended) or on any data field. Parts of the data field can be masked. Parts with "X" are irrelevant for the trigger function. In Figure 19 all messages containing a 02hex as the second data byte are being triggered. Additionally, the user can configure the number of frame messages after the trigger point and the behavior after their reception:

- "stop receiving" stops the recording of the message frames in the receive window
- "stop CAN controller" deactivates the CAN controller. All sending action in "Protocol Monitor Transmit" will be stopped.
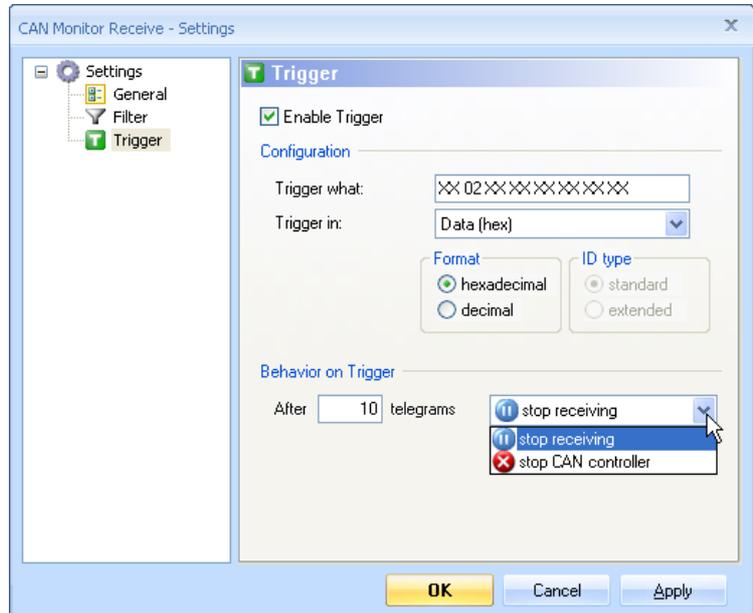
Figure 20: Trigger options

4.15.3 Module: CAN Receive

License note:

Receiving of CAN messages is only available if the corresponding software module is supported by the connected CAN-Bus Tester 2. (see Section 6 „License Management"). The software modules supported by the device are listed in the information dialog (menu: "*Help*"→ "*About CAN-Bus Tester 2*").

The following additional functions are provided by the menu and the toolbar:

	Symbolic Decoding	Activates symbolic decoding for all received CAN messages.
	Switch ID display	enabled: display hexadecimal
		disabled: display decimal
	Switch data display	enabled: display hexadecimal
		disabled: display decimal

The "Module CAN" option serves to receive and display CAN messages. There are two modes of display:

"Scroll" mode: Presentation of the CAN messages in the order in which they are received (Figure 21)
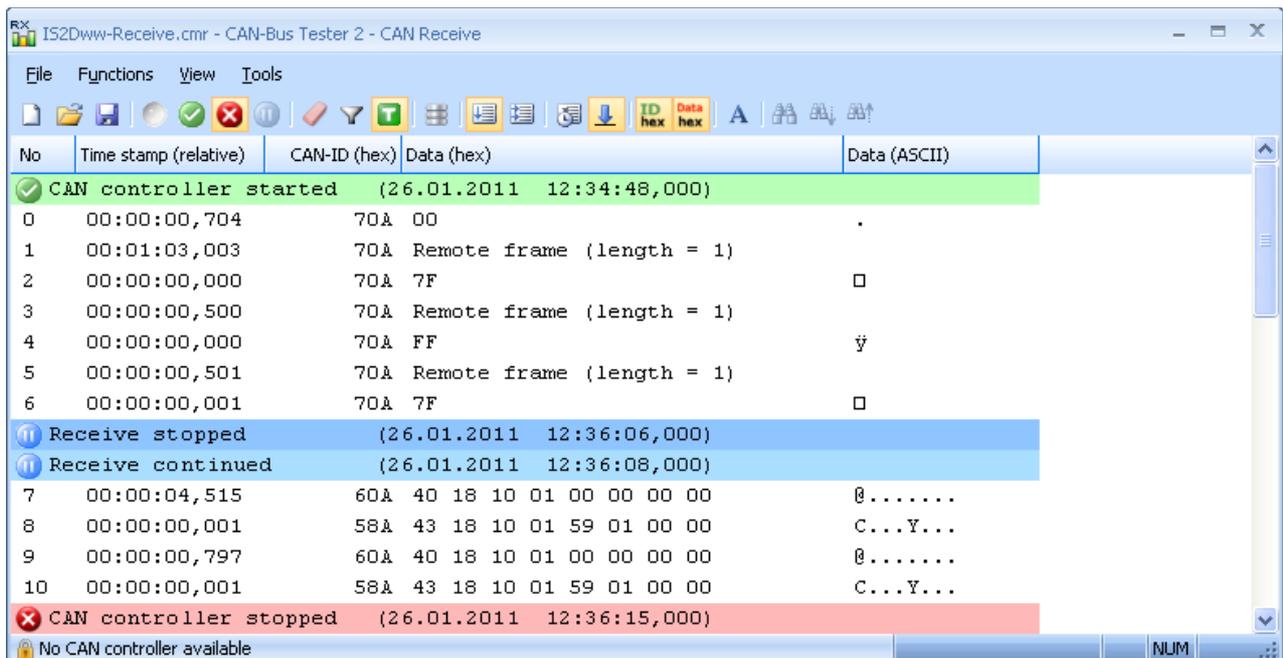
Figure 21: Module: CAN Receive - "Scroll" mode

"Overwrite" mode: Presentation of the received CAN messages sorted by their CAN ID. (Figure 22)
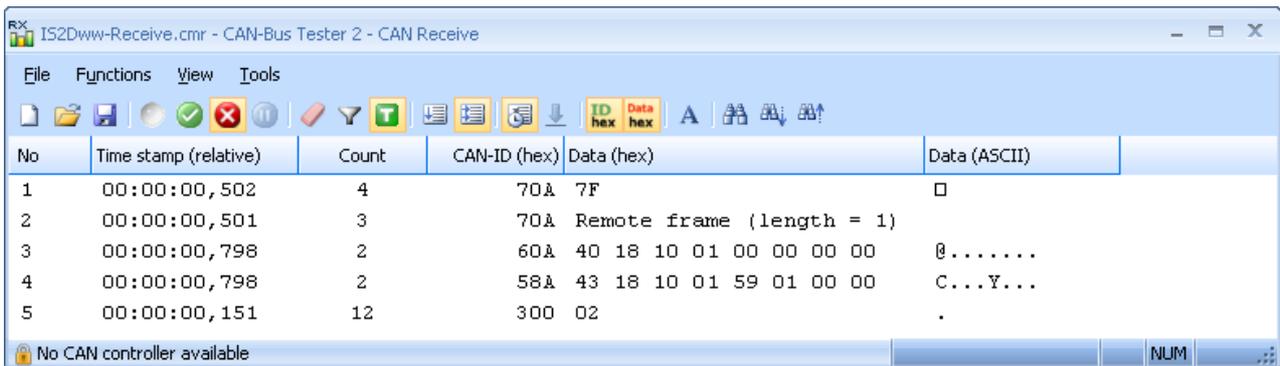
Figure 22: Module: CAN Receive - "Overwrite" mode

Symbolic Decoding

CAN messages can be displayed as a symbol to relieve their interpretation. Their representation is adapted via a symbol file. If symbolic representation is selected, the CAN IDs are displayed by their symbolic names. The sequences of bits of a CAN message are marked as signals with names. These signals can display the raw data transmitted by CAN either in decimal or hexadecimal format or - if requested - convert them automatically and show them as a physical value with its unit. With the descriptions of the values (Enums) certain variables can be displayed alphanumerically. Different definitions of the data can be determined in a CAN ID by multiplexers.

For decoding the messages, the CAN-Bus Tester 2 uses a symbol file. Symbol files can be created by using the free of charge symbol editor **CANsymEdit**. Select one symbol file to be used for the representation.

A detailed description of the creation of symbol files is available in the user manual of the symbol editor.
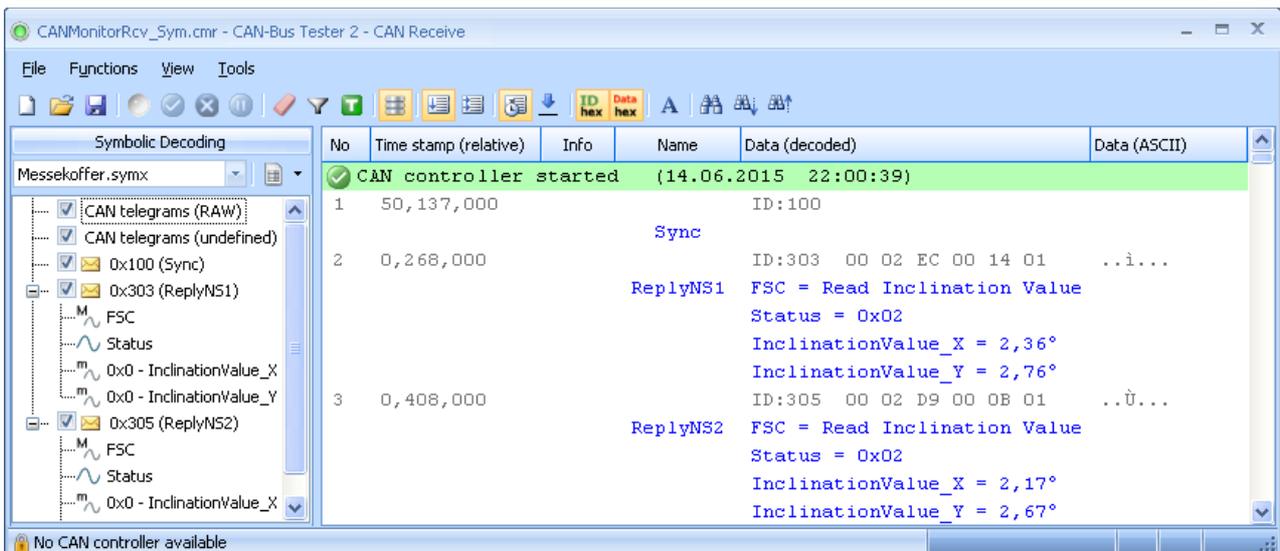
Figure 23: Module: CAN Receive - Symbolic decoding

4.15.4 Module: CANopen Receive

License note:

Receiving of CANopen messages is only available if the corresponding software module is supported by the connected CAN-Bus Tester 2. (see Section 6 „License Management"). The software modules supported by the device are listed in the information dialog (menu: "*Help*"→ "*About CAN-Bus Tester 2*").

The module "CANopen Receive" serves as a monitoring tool for the analysis of CANopen-based systems. It interprets all received messages according to the CANopen specification. The messages are recognized as SDO, PDO, NMT, Sync, Time stamp, heartbeat and emergency objects and interpreted accordingly.

The following additional function is provided by the menu and the toolbar:

	Buffered SDO transfer	Shows the multi-part SDO transfer as overall access or as single messages. (CANopen only)

There are two modes of display:

- Mode Scroll: Presentation of the CANopen messages in the order in which they are received
- Mode Overwrite: Presentation of the received CANopen messages sorted by object type.
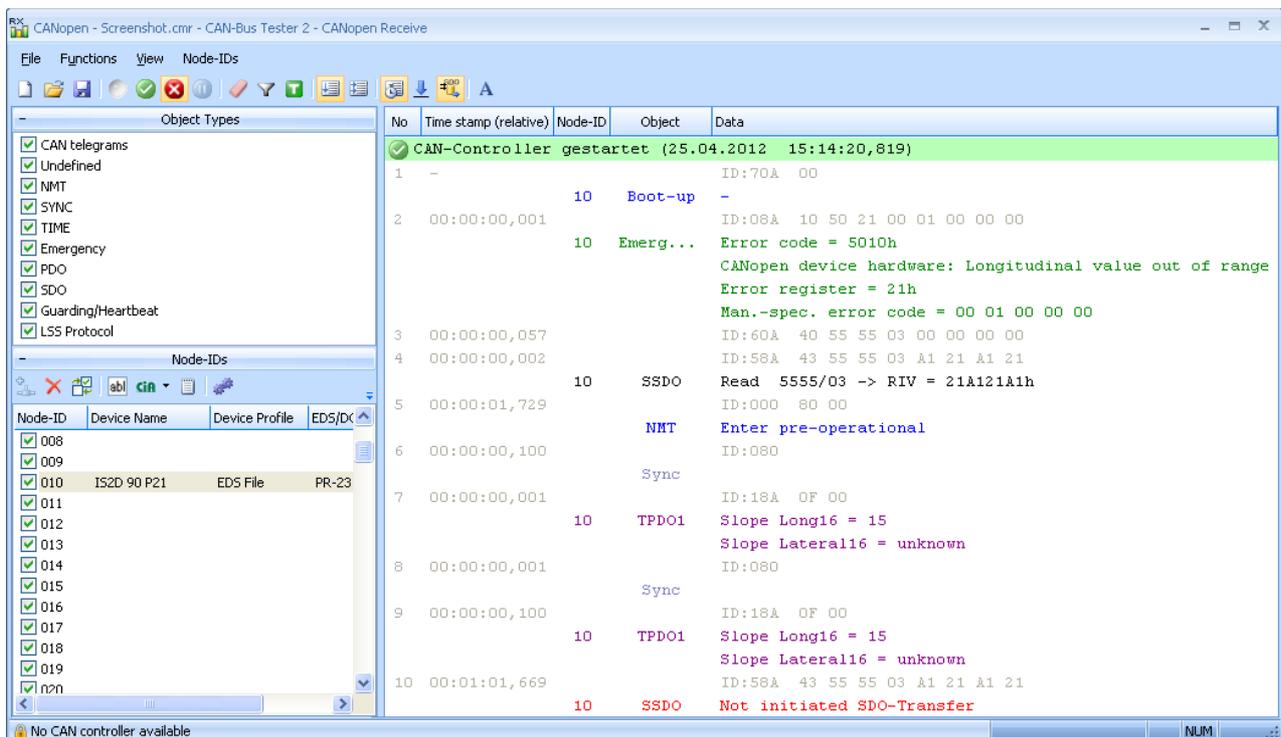
Figure 24: Module: CANopen Receive

Filter configuration:

The filtering of the CANopen messages can be done for object types and node number (Node-ID) by checking the appropriate checkboxes.

Node configuration:

The basis for the interpretation of CAN messages is the device description of the individual CANopen nodes. This description can be done for each device/node (Node-ID) by loading the corresponding EDS / DCF file. If no file is available, the device description can be made by selecting the device profile. In addition a manual configuration of each node number is also possible. (Figure 25)
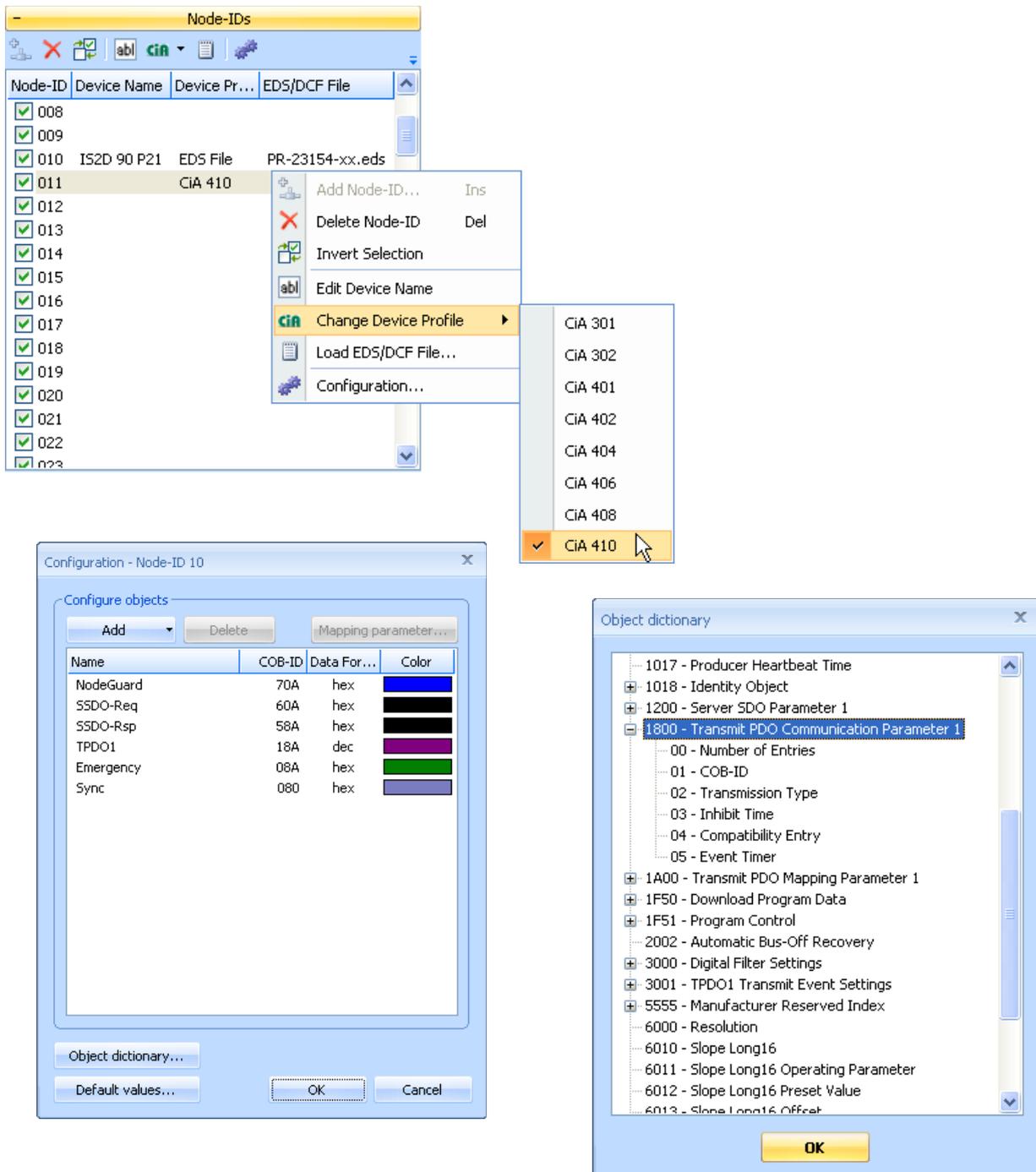
Figure 25: Node configuration (Node IDs)

5 The „CAN-Bus Tester 2 Scan" Program

Figure 26: CAN-Bus Tester 2 Scan

The "CAN-Bus Tester 2 Scan" program provides a quick overview of the type and serial number of the connected CAN-Bus Tester 2. The program is entered in the Autostart folder and is called automatically with each system start. For each CAN-Bus Tester 2 detected, a symbolic icon . appears in the info area of the task bar. When you click with the mouse on this icon, the menu shown in Figure 26 is opened. Use this menu to call the CBT2 application software and the manual directly.

Note:

If this program is not required, the link can be deleted from the Autostart folder.

6 License Management

The CAN-Bus Tester 2 is available in a basic version with the bus system **CAN**. This basic version is delivered in the case complete with all accessories (see Section 8.1 "Scope of Supply - Basic Set").

Optional bus system such as **CANopen**, **DeviceNet** and **SAE J1939** as well as the optional protocol monitor can be activated via licenses at any time.

On purchase of licenses for additional bus systems or the protocol monitor a license file (*.cbt2lic) is provided. This license file can be downloaded to the connected CAN-Bus Tester 2 via the button "Load License" in the information dialog (Figure 27). The license is only valid for a tester with a specific serial number and can only be loaded on this tester.
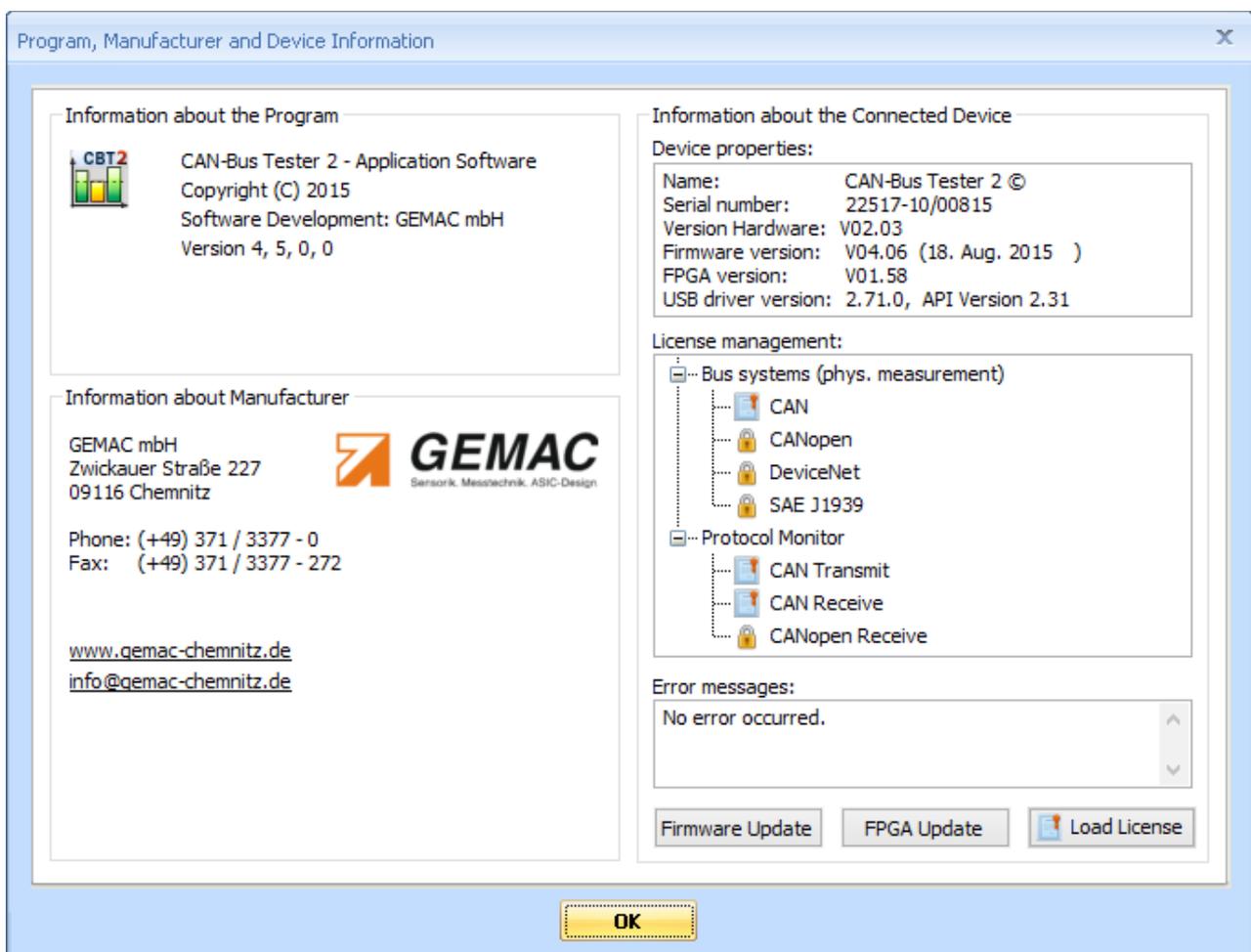
Figure 27: License management in information dialog

7 Technical Specifications

General parameters and overview of functions	
Bus systems	CAN (ISO11898-2), CANopen, DeviceNet (EN 50325-2), SAE J1939
Bit sampling	64-fold, 10,240 sampling points
Bit timing	Adjustable BTL cycles (tq), sample point and resynchronization jump width (SJW)
Supported baud rates	Depending on bus system: 10; 20; 50; 100; 125; 250; 500; 800; 1000 kbit/s Additionally user-defined: 5; 33.3; 62.5; 75; 83.3; 200 kbit/s Automatic detection via baud rate scan
List of stations	Automatic detection via Station scan Designation, CAN ID, ID type, Node ID, MAC ID, Source address, can also be entered manually
List of Measurements	Possibility to measure at different measuring points and at different times Sorting by measurement type, measuring point and measurement time
Quality level	Value representing the signal quality (0 ...100%) Minimum value and maximum values saved Time stamp
Disturbance-free voltage range and edges	Disturbance-free voltage range (typ. -0,75 ... 3 V, resolution 50 mV) Edge steepness (falling and rising, specified in 1/64th of the bit width) Minimum value and maximum values saved
Oscilloscope display	Trigger on message frames with specified ID, trigger position can be set Frame analysis and full frame recording Decoding according to protocol (CAN, CANopen, DeviceNet, SAE J1939) Zoom (six stages)
Online trigger	Real-time monitoring of the bus for logical and physical errors Resolution can be set (10 ms ... 1 min) Oscilloscope display and e-mail notification on triggers
Automatic evaluation	Limit value settings and measured-value evaluation according to: • critical quality level • critical disturbance-free voltage range • critical edge (rising and falling)
Bus status	Bus traffic detection (display: dominant, recessive, not defined, bus traffic)
Bus traffic load	Permanent display of the bus traffic load (0 ... 100%), Minimum and maximum values saved
Error frames	Constant display of detected frame errors Distinction between active and passive error frames (0 ... >50.000)
Protocol monitor	CAN: Reception of CAN message frames incl. filtering, Transmission of CAN message frames and sequences (message lists) CANopen: Interpretation of all CAN messages according to the CANopen spec as SDOs, PDOs, NMT-, Heartbeat-, Emergency-, Sync- and Timestamp (CiA301, CiA302, CiA305, CiA401, CiA402, CiA404, CiA406, CiA408, CiA410, upgradeable)
Test record	Comprehensive, configurable measuring and test record on DIN A4: • Letterhead with tester and customer contact data • Tabular representation of the measured values • Graphic representation of the measured values
Export function	Measuring data as a configurable CSV file Graphical measured-data representation as a configurable bitmap (.bmp,.jpg,.png)
Firmware and FPGA configuration	can be updated via USB
CE conformity	
Equipment safety	EN 60950-1:2006/A1:2010
EMC • Low-frequency interference emission: • High-frequency interference emission: • Interference immunity:	EN 61000-3-2:2006/A1:2009/A2:2009 EN 55022:2006/A1:2007 EN 61000-6-2:2005/AC:2005

Table 1: Technical specifications

Electrical parameters	
Power supply	Via the supplied wide-range power supply pack (9 ... 36 V DC)
Current consumption	0.55 ... 0.15 A
Measuring of the differential voltage	typ. -0.75 V ... 3.00 V
Measuring of the loop resistances	typ. 0 Ω ... 800 Ω
Measuring of the cable length	typ. 0 m ... 500 m • 0...100 m: Resolution: 0.5 m, Accuracy: 3 % ± 1,5 m • 100...500 m: Resolution: 1.0 m, Accuracy: 10 % ± 10 m for a signal runtime of: 4.5 ns/m for CAN/CANopen/SAE J1939 4.3 ns/m for DeviceNet
Measuring of the CAN supply voltage	0 ... 36 V
Potential difference between the connections CAN bus, USB and oscilloscope	< 50 V DC (or < 71 V AC)
Trigger output for the oscilloscope	BNC socket, electrically isolated, H pulse, approx. 2 bits wide, level approx. 5 V
Mechanical parameters	
Supply voltage connection	Extra-low voltage socket
CAN connection	2 x 9-pin D-Sub connector
PC connection	Self-powered device to USB Specification 1.1, electrically isolated
Trigger output for the oscilloscope	BNC socket, electrically isolated
Housing	Aluminum sheet housing
Temperature range	Operation: 5 °C ... 40 °C Storage: -20 °C ... 60 °C
Humidity	Operation: 20 % ... 80 % (non-condensing) Storage: 20 % ... 80 % (non-condensing)
Degree of protection of the housing	IP20 to EN 60529
Dimensions (Device / Case)	170 mm x 134 mm x 40 mm / 504 mm x 354 mm x 119 mm
Weight (Device / Case)	Approx. 600 g / Approx. 5000 g

Table 2: Technical specifications (cont'd)

Warning:

The CBT2 is a Class A device. Such devices can cause interference in residential areas. In this case, the plant operator can be required to take appropriate measures and to bear the costs of such measures.

8 Scope of Supply

8.1 Scope of Supply - Basic Set

The scope of supply of the CAN-Bus Tester 2 comprises the following:

- CAN-Bus Tester CBT2
- CAN bus accessories:
    - 6 adapter sets (D-Sub 9, Open style, M12, 7/8", SAE J1939-11, SAE J1939-13)
    - Adapter board (for simple connection of oscilloscope probes)
    - USB cable (3 m)
    - BNC cable (1.5 m)
- Power supply:
    - AC/DC adapter:
        - Type: Desk power pack
        - Input voltage: 100 ... 240 V, 50 Hz ... 60 Hz
        - Output voltage (DC):   24 V, 500 mA,
        - Connection cable: 2 m length with extra-low-voltage plug
    - Mains power cable (1.8 m):
        - Country variants: Europe, Great Britain, U.S.A./Japan, (Australia possible)
- User Manual
- Product CD with USB driver and application software
- robust lockable case (incl. keys)

8.2 Content adapter sets

Adapter set	Content
Adapter set 1: D-Sub 9	• Adapter cable 1 • Shorting plug 1 • Terminating resistor
Adapter set 2: Open style	• Adapter cable 2 • Shorting plug 2 • Adapter for Open style
Adapter set 3: M12	• Adapter cable 3 • Shorting plug 3 • Terminating resistor • T-piece
Adapter set 4: 7/8"	• Adapter cable 4 • Shorting plug 4 • Terminating resistor • T-piece
Adapter set 5: SAE J1939-11	• Adapter cable 5 • Shorting plug 5 • Terminating resistor • Y-piece
Adapter set 6: SAE J1939-13	• Adapter cable 6

Table 3: Content adapter sets

9 Maintenance and Customer Service

9.1 Maintenance

The CAN-Bus Tester 2 is maintenance-free. Calibration is not necessary. Any repairs must only be performed by the manufacturer.

9.2 Customer service

9.2.1 Shipping

If you send the CAN-Bus Tester 2 for repair, use only the original or equivalent packaging. Please give a brief error description and your telephone number in case we have any questions.

9.2.2 Support

If you have any technical questions, please specify the serial number of your device, its firmware and hardware configuration version and the version of the CBT2 application software. Please direct questions to your supplier or else contact the hotline of the CAN-Bus Tester 2 manufacturer.

Manufacturer: GEMAC - Gesellschaft für Mikroelektronikanwendung Chemnitz mbH

Zwickauer Str. 227

09116 Chemnitz

Phone +49 371 3377 - 0

Fax +49 371 3377 - 272

Web http://www.gemac-chemnitz.de

E-mail info@gemac-chemnitz.de

9.2.3 Warranty and limitation of liability

We will assume a warranty of 24 months for the CAN-Bus Tester 2, commencing from the date of delivery. Any repairs required during this time and which fall under the manufacturer's obligation to give a warranty will be performed free of charge. Any damage resulting from improper use of the device or from exceeding of the specified technical parameters is not covered by the manufacturer's obligation to give a warranty.

GEMAC will only be liable for consequential damage resulting from use of the product in case of deliberate action or gross negligence.

The General Terms and Conditions of GEMAC - Gesellschaft für Mikroelektronikanwendung Chemnitz mbH will apply.

10 Ordering Information

Product	Description	Article No.
Basic set		
CAN-Bus Tester 2	CAN-Bus Tester 2 basic version Bus system: CAN complete scope of supply see section 8.1 "Scope of Supply - Basic Set"	PR-22517-10
Licenses for optional bus systems (phys. measurement)		
CANopen	License key for bus system CANopen	SW-22517-01
DeviceNet	License key for bus system DeviceNet	SW-22517-02
SAE J1939	License key for bus system SAE J1939	SW-22517-03
Licenses for optional Protocol Monitor		
CAN Transmit, CAN Receive	License key for Protocol Monitor CAN (transmit / receive)	SW-22517-10
CANopen Receive	License key for Protocol Monitor CANopen (receive)	SW-22517-11
Accessories for additional country variants		
Mains power cable Australia	Mains power cable for Australia for AC/DC adapter	KB-00093-03

Table 4: Ordering information

10.1 Spare parts

Product	Description	Article No.
Mains power cable Euro	Mains power cable for Europe for AC/DC adapter	KB-00093-00
Mains power cable U.K.	Mains power cable for Great Britain for AC/DC adapter	KB-00093-01
Mains power cable U.S.A./Japan	Mains power cable for U.S.A. / Japan for AC/DC adapter	KB-00093-02
Adapter board	CAN bus adapter to connect the CBT2 with an oscilloscope	LP-10235-51
USB cable	Connection between CBT2 and PC	PR-00211-00
BNC cable	Connection between trigger port and oscilloscope	KB-03032-00
AC/DC adapter	Desk power pack, 100 ... 240 V; 50 Hz ... 60 Hz; 24 V/500 mA	BG-00177-00
Adapter set D-Sub 9		
Adapter cable 1	Connecting cable to connection to CBT2 with D-Sub 9 bus connector	KB-03021-01
Shorting plug 1	D-Sub 9 shorting plug for wiring test	BG-00171-00
Terminating resistor	D-Sub 9 connector with terminating resistor	ST-03058-00
Adapter set Open style		
Adapter cable 2	Connecting cable to connection to CBT2 with Open style bus connector	KB-03022-01
Shorting plug 2	Open style shorting plug for wiring test	BG-00172-00
Open style adapter	Open style adapter with socket (two screw terminals per contact)	BU-03068-00
Adapter set M12		
Adapter cable 3	Connecting cable to connection to CBT2 with M12 bus connector	KB-03023-01
Shorting plug 3	M12 shorting plug for wiring test	BG-00173-00
Terminating resistor	M12 connector with terminating resistor	ST-03008-00
T-piece	M12 branch connector	ST-03007-00
Adapter set 7/8"		
Adapter cable 4	Connecting cable to connection to CBT2 with 7/8" bus connector	KB-03115-00
Shorting plug 4	7/8" shorting plug for wiring test	ST-03045-00
Terminating resistor	7/8" connector with terminating resistor	ST-03060-00

Product	Description	Article No.
T-piece	7/8" branch connector	ST-03043-00
Adapter set SAE J1939		
Adapter cable 5	Connecting cable to connection to CBT2 with SAE J1939-11 bus connector	KB-03114-00
Adapter cable 6	Connecting cable to connection to CBT2 with SAE J1939-13 bus connector	KB-03113-00
Shorting plug 5	SAE J1939-11 shorting plug for wiring test	BG-03005-00
Terminating resistor	SAE J1939-11 connector with terminating resistor	BU-03097-00
Y-piece	SAE J1939-11 branch connector	ST-03056-00

Table 5: Ordering information - Spare parts

11 Problem Recovery

The following chapter will help you if you have problems with your CAN-Bus Tester 2. This chapter lists typical error sources and problem situations, indicates possible causes and offers possible solutions.

If you encounter a problem with your CBT2 and/or the application software which is not listed here or cannot be solved by the solutions specified here, please contact the manufacturer (see Section 9.2.2 „Support").

11.1   Problems with the CBT2 device setup

Problem	Questions, causes & problem recovery
CAN-Bus Tester 2 is not detected: • Error in the Windows® setup for the device • Driver not found • "No CAN-Bus Tester 2 connected"	Questions: • CBT2 connected to PC and power supply ("ON" LED)? • Does the USB hardware of your PC function correctly? • Is "CAN-Bus Tester 2" displayed under "USB" in the device manager? • Is the correct operating system installed (see Section 4.2 "Installing the software")? How to solve this problem: • Disconnect the CAN-Bus Tester 2 from PC and from the mains. • If necessary uninstall the CBT2 application software (e.g. via the Control Panel) • Install the CBT2 application software (see Section 4.2 "Installing the software") • Reboot your PC. • Connect the CAN-Bus Tester 2 to the mains power (AC/DC adapter) and your PC (USB cable). • Windows® should now detect a new device and install the appropriate drivers.
• CBT2 is recognized by the device manager and CAN-Bus Tester 2 Scan, but operator software displays "No CAN-Bus Tester 2connected"	How to solve this problem: • Open the Select device dialog under "*Tools*" → select "*CAN-Bus Tester 2*" and choose one of the CBT2 devices from the list.

11.2   Problems when measuring

Problem	Questions, causes & problem recovery
Wiring test	
• Button is disabled (hidden)	Questions: • CBT2 operated on the supplied power pack (not via the plant CAN bus)? • CBT2 connected to the PC and to the plant CAN bus? • All bus stations removed / no bus traffic (bus status LED = yellow)? • CAN supply voltage display: approx. 0.0 V? How to solve this problem: • Realize the above prerequisites
Baud rate scan	
• Button is disabled (hidden)	Questions: • CBT2 connected to PC and power supply ("ON" LED)? • CBT2 detected by application software (→ status bar)? • CBT2 correctly connected to plant CAN bus? • Level change present on the bus (bus status LED = green)? How to solve this problem: • Provide for transmission activity on the CAN bus
• No baud rate detected	Possible causes: • Incorrect bus installation (→ excessive reflections) • Excessive interference affecting the line • Defective CAN bus driver • Line short-circuits • Unsupported baud rate selected How to solve this problem: • Correct the baud rate manually or try a different baud rate. • Perform the wiring test
Station scan	
• Button is disabled (hidden)	Questions:

Problem	Questions, causes & problem recovery
	• CBT2 connected to PC and power supply ("ON" LED)? • CBT2 detected by application software (→ status bar)? • CBT2 correctly connected to plant CAN bus? • Level change present on the bus (bus status LED = green)? How to solve this problem: • Provide for transmission activity on the CAN bus
Error frame counter	
• Counts continuously	Possible causes: • An incorrect baud rate has been selected (→ Baud rate scan) • There is an error in the physical bus characteristics and there are significant signal faults.
"All Stations", "One Station" and "Online Trigger" measurements	
• cannot be started	Questions: • CBT2 connected to PC and power supply ("ON" LED)? • CBT2 detected by application software (→ status bar)? • CBT2 correctly connected to plant CAN bus? • At least one station highlighted in the List of stations as "*to be measured*"? Additionally for the "Measurement One Station": • One station selected? How to solve this problem: • Provide for transmission activity on the CAN bus
Printing and exporting	
• The relevant data field is disabled	How to solve this problem: • Perform the desired measurement for the station(s).

12 Notes

Document: 22510-HB-1-11-E-CAN-Bus Tester 2