



Communication protocol Spinel used in converters AD4xxx

Complete protocol description
+ Hysteresis principal addition



Spinel in AD4xxx

Datasheet

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DESCRIPTION

This is document describing communication protocol in AD4RS, AD4USB and AD4ETH converters. Complete hardware documentation and functionality description is at disposal on our WEB site <http://www.papouch.com/> (detailed documentation also available in PDF).

The default communications protocol is Spinel. Switching between protocols (also switching to ModBus) is described on page 49.

Basic communication parameters:

AD4RS

| | |
|------------------------------|---|
| Communication line..... | RS232 and RS485 |
| Communication speed | adjustable 300 Bd to 230,4 kBd (default: 9,6 kBd) |
| Number of data bits..... | 8 |
| Parity..... | no parity |
| Number of stop-bits..... | 1 |
| Minimum response delay | 2 ms ¹ |

AD4USB

| | |
|---------------------------|--------------------------------------|
| Communication line..... | USB version 1.1 (USB 2.0 compatible) |
| Communication speed | 115 200 Bd (fixed) |
| Data bits..... | 8 |
| Parity..... | none |
| Stop bits..... | 1 |

AD4ETH

| | |
|--------------------------------------|--------------------|
| Communication line..... | 10/100 Ethernet |
| Default IP address | 192.168.1.254 |
| Default network mask..... | 255.255.255.0 |
| Default gateway | 0.0.0.0 |
| Default port number for TCP | 10001 |
| Virtual port – communication speed.. | 115 200 Bd (fixed) |
| Virtual port – data bits | 8 |
| Virtual port – parity..... | none |
| Virtual port – stop bits | 1 |

¹ Due to the delay when switching the communication direction over to RS485.

Change log

Version 04

Added standard current resolutions 0 – 20 mA and 4 – 20 mA. This change is related to instructions 1AH (Measurement type settings), 1BH (Measurement type read), 1EH (Conversion and display settings) and 1FH (Conversion and display read).

- 1AH/1BH: Added value 02H in Measurement type parameter.
- 1EH/1FH: Added parameter Type, identical to parameter in instructions 1AH/1BH.

Corrected description of input parameters in 1BH instruction (Measurement type read). This instruction was already without input parameters in version 2. Always sends all channels' settings in response.

COMPLETE DESCRIPTION OF SPINEL PROTOCOL

Standardized protocol Spinel is implemented to all AD4 modules in formats 66 (ASCII) and 97 (binary). AD4xxx communicates using this protocol in case of TCP/IP or UDP/IP level of communication.

Format 97

Format 97 uses 8bit bytes for communication (0 to 255 in decadal range). For easy communication debugging can be used Spinel Terminal. Instructions are split to Requests and Responses.

Structure

Request:

PRE FRM NUM NUM ADR SIG INST DATA... SUMA CR

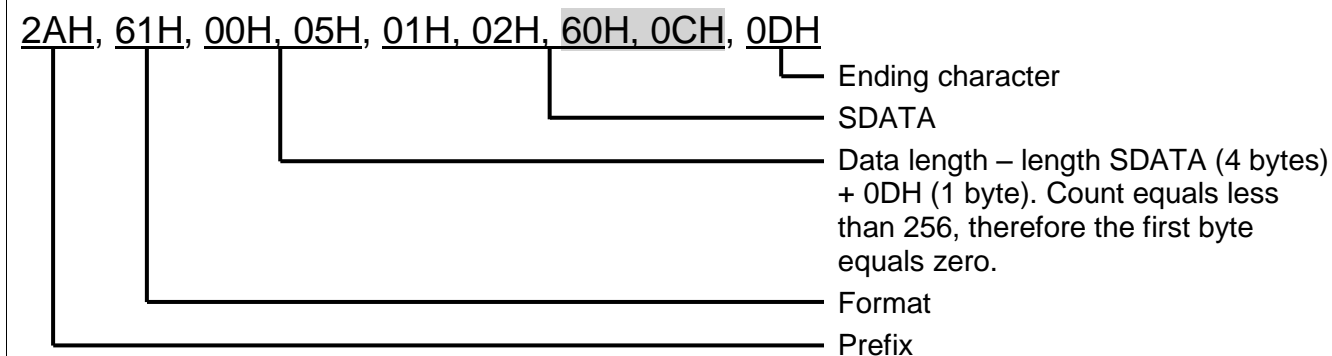
Response:

PRE FRM NUM NUM ADR SIG ACK DATA... SUMA CR

| | |
|-------------------------|--|
| PRE | Prefix, 2AH (character “*”). |
| FRM | Format number 97 (61H). |
| NUM | Byte count of the instruction from following byte to the end of the frame. |
| ADR | Address of the module sending request or responding to it. |
| SIG | Instruction signature – any number in range from 00H to FFH. The same number sent in request returns in response to determine which request the response replies on. |
| INST² | Instruction code – Module instructions are described in detail in chapter “Complete instructions overview” on page 10. |
| ACK | Request confirmation (Acknowledge); if and how was the request performed. ACK lies in interval of 00H to 0FH. |
| DATA² | Data. Described in detail in chapter “Complete instructions overview” (page 10) for each instruction. |
| SUMA | Checksum. |
| CR | Ending character (0DH). |

Glossary

Example



² Data and Instructions are highlighted like this.

Data Length (NUM)

Sixteen-bit value defining the number of bytes until the end of the instruction; number of all bytes found after NUM up to CR (including). It takes the values from 5 to 65535. If lower than 5, the instruction is considered faulty and it is answered (if intended for the relevant device) with ACK "Invalid Data" instruction.

Process of NUM creation:

Ad up the number of bytes following both NUM bytes (i.e. the number of SDATA bytes + 1 CR byte). View the resulting sum as a sixteen-bit number. Divide it into the upper and lower byte. The first NUM byte is the upper byte of the amount, the second NUM byte is the lower byte of the amount. (If the amount of bytes is lower than 256, the first NUM byte is 00H.)

Address (ADR)

The FFH address is reserved for broadcast. If the enquiry contains the FFH address, the device operates as if its own address is entered. No response is sent to enquiries with this address.

The FEH address is a universal address. If the enquiry contains the FEH address, the device operates as if its own address is entered. The device enters real, currently set address into the response. The universal address is used in cases where only one device is connected on the line.

Enquiry Acknowledgement (ACK)

ACK informs the superior device on the way of the received instruction processing. Acknowledgement codes:

- 00HEVERYTHING OK
The instruction was properly received and completely executed.
- 01HUNSPECIFIED ERROR
Unspecified device error.
- 02HINVALID CODE OF INSTRUCTION
The received instruction code is unknown.
- 03HINVALID DATA
Data are of invalid length or contain an invalid value.
- 04HENTRY NOT ALLOWED/ACCESS DENIED
 - The enquiry was not performed, as some conditions had not been fulfilled.
 - Attempt to enter data into inaccessible memory.
 - Attempt to activate a device function requiring a different configuration (e.g. higher communication speed).
 - Attempt to change configuration without previous setup permission.
 - Access into memory protected by a password.
- 05HDEVICE FAILURE
 - Device failure requiring service action.
 - Device internal memory error or setup memory error.
 - Device internal error (operation error or start-up error).
 - Any other error affecting the device proper functioning.
- 06HNO DATA AVAILABLE
- 0DH.....INSTRUCTION SENT AUTOMATICALLY – CHANGE OF DIGITAL INPUT STATE
- 0EH.....INSTRUCTION SENT AUTOMATICALLY – CONTINUOUS MEASURING
 - Periodical sending of measured values.
- 0FHINSTRUCTION SENT AUTOMATICALLY – LIMITS OR RANGE EXCEEDING

Check Sum (SUMA)

The sum of all instruction bytes (added all transmitted data except for CR) subtracted from 255.

Calculation: $SUMA = 255 - (PRE + FRM + NUM + ADR + SIG + ACK (INST) + DATA)$

Incorrect checksum is not answered. (Device is waiting for CR even if checksum is incorrect.)

Format 66

Format 66 uses only decimal variables or character that can be typed in using a usual keyboard. That makes this format suitable for synchronizing applications with Spinel. Pauses between individual characters must not be longer than 5 seconds. The instructions are divided into enquiry – response:

Structure

Request:

PRE FRM ADR INST DATA... CR

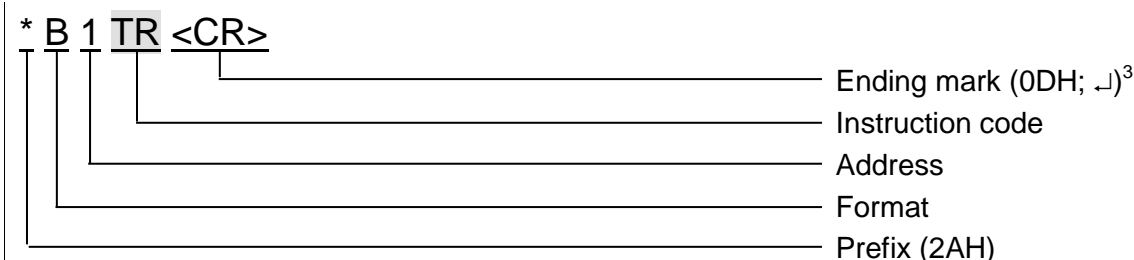
Response:

PRE FRM ADR ACK DATA... CR

| | |
|-------------------------|--|
| PRE | Prefix, 2AH (character “*”). |
| FRM | Number of Format 66 (character „B“). |
| ADR | Address of the module that receives request or sends response. |
| INST² | Instruction code – Instruction codes of a given device. Those are ASCII codes of letters „A“ to „Z“ and „a“ to „z“ and numbers „0“ to „9“. Instructions of the module are described in detail in chapter Complete instructions overview (page 10). |
| ACK | Request acknowledge, if and how was the request performed. ACK lies in interval 00H to 0FH. |
| DATA² | Data. Carried instructions in ASCII code. It is recommended to carry the data in ordinary shape and units. DATA can contain neither prefix nor CR. in detail in chapter Complete instructions overview (page 10). |
| CR | Ending mark (0DH). |

Glossary

Example – single measure



Address (ADR)

Address is one character which unambiguously identifies and distinguishes a particular device from others on a single communication line. A device always uses this number for its identification in responses to enquiries from the superior system. The following ASCII characters can form an address: numbers “0” to “9”, lower case letters “a” to “z” and capital letters “A” to “Z”. The address must not be identical with a prefix or CR.

The “%” address is reserved for broadcast. If the enquiry contains the “%” address, the device operates as if its own address is entered. No response is sent to enquiries with this address.

³ Ending mark <CR> is not written out in examples from chapter Complete Instructions overview (replaced by character ↵.)

The "\$" address in the universal address. If the enquiry contains the "\$" address, the device operates as if its own address is entered. The device enters real, currently set address into the response. The universal address is used in cases where only one device is connected on the line.

Instruction Code (INST)

Device instruction code.

If a valid instruction is received (correct ADR) and a flag of the received message is set,, the device must respond to such instruction.

Enquiry Acknowledgement (ACK)

ACK informs the master device about the performance of received request.

Acknowledge codes:

- 0.....EVERYTHING OK
The instruction was properly received and completely executed.
- 1.....UNSPECIFIED ERROR
Unspecified device error.
- 2.....INVALID CODE OF INSTRUCTION
The received instruction code is unknown.
- 3.....INVALID DATA
Data are of invalid length or contain invalid value.
- 4.....ENTRY NOT ALLOWED/ACCESS DENIED
 - The enquiry was not performed, as some conditions had not been fulfilled.
 - Attempt to enter data into inaccessible memory.
 - Attempt to activate a device function requiring a different configuration (e.g. higher communication speed).
 - Attempt to change configuration without previous setup permission.
 - Access into memory protected by a password.
- 5.....DEVICE FAILURE
 - Device failure requiring service action.
 - Device internal memory error or setup memory error.
 - Device internal error (operation error or start-up error).
 - Any other error affecting the device proper functioning.
- 6.....NO DATA AVAILABLE
- DINSTRUCTION SENT AUTOMATICALLY – CHANGE OF DIGITAL INPUT STATE
- EINSTRUCTION SENT AUTOMATICALLY – CONTINUOUS MEASURING
 - Periodical sending of measured values.
- F.....INSTRUCTION SENT AUTOMATICALLY – LIMITS OR RANGE EXCEEDING

Data (DATA)

Instruction data.

COMPLETE INSTRUCTIONS OVERVIEW

| Instruction | Code 97 | Code 66 | Page |
|--|----------------|----------------|-------------|
| Measuring | | | |
| Single measuring | 51H | MR0 | 11 |
| Continuous Measuring – start..... | 52H | MC | 13 |
| End of measuring | 53H | | 18 |
| Continuous Measuring Setup | 54H | | 19 |
| Reading settings of continuous measuring..... | 55H | | 19 |
| Communication line and address settings | | | |
| Configuration Permission | E4H | E | 20 |
| Communication Parameters Setup..... | E0H | AS a SS | 21 |
| Communication Parameters Reading..... | F0H | CP | 23 |
| Address Setup using Serial Number | EBH..... | | 24 |
| Calibration | | | |
| Calibration constants writing..... | 12H | | 25 |
| Reading of calibration constants | 13H | | 26 |
| Measurement type setting | 1AH | | 26 |
| Reading of measurement type settings | 1BH | | 27 |
| RAW measurement..... | 5FH | | 27 |
| Additional | | | |
| Name and version reading | F3H | ? | 28 |
| Manufacturer data reading | FAH | | 29 |
| User Data Saving | E2H | DW | 30 |
| Saved User Data Reading..... | F2H | DR..... | 31 |
| Input Name Saving | 2BH | | 32 |
| Reading of input title..... | 3BH | | 33 |
| Status Setup..... | E1H | SW | 34 |
| Reading of status | F1H | SR..... | 35 |
| Reading of communication errors..... | F4H | | 36 |
| Checksum Permission..... | EEH..... | | 37 |
| Checksum – settings reading | FEH..... | | 37 |
| Reset..... | E3H | RE | 38 |
| Auxiliary Instructions | | | |
| Single Measurement with Conversion | 58H | | 39 |
| Conversion and Display Setup | 1EH | | 40 |
| Conversion and Display Reading | 1FH | | 43 |
| Values Monitoring Setup | 1CH | | 44 |
| Reading the settings of values monitoring..... | 1DH..... | | 48 |

To keep the lucidity, Instructions (INST), acknowledgement (ACK) and data (DATA) are described in detail. Address (ADR), Signature (SIG) and CheckSum (SUMA) are described in detail in upper part of the document where the protocol is described.

Measuring

Single measuring

This instruction reads last measured values from all channels of the converter.

Request:

Instruction code: 51H

Parameters: (const)

| const | Constant | length: 1 byte |
|---|----------|----------------|
| Constant 00H. This byte ensures compatibility with other devices and allows further features installed. | | |

Response:

Acknowledge code: ACK 00H

Parameters: {(chn₁)(status₁)(value₁)} {...} {...} {(chn₄)(status₄)(value₄)}

| chn | Channel number | length: 1 byte |
|--|----------------|----------------|
| This byte designates channel number and it holds for all following bytes until next <i>chn</i> byte. In essence that means that following bytes (status, value) attach to channel with designated number. From range 01H to 04H depending on channel number. | | |

| status | Status of the measured-out value | length: 1 byte |
|---|---|----------------|
| Status of measured-out value for the channel with the number stated in <i>chn</i> byte. | | |
| bit 3,2 | 00 = value is in measuring range | |
| | 01 = value is below the lower limit (underflow) | |
| | 10 = value is above upper limit (overflow) | |
| bit 7 (MSb) | 0 = invalid value | |
| | 1 = valid value | |

| value | Measured-out value | length: 2 bytes |
|---|--------------------|-----------------|
| Measured value from the channel with number stated in previous byte <i>chn</i> . 16-bit number from range 0 – 10 000. Bytes are in order MSB:LSB. | | |

Examples:

| |
|---|
| Request: |
| 2AH, 61H, 00H, 06H, 31H, 02H, 51H, 00H, EAH, 0DH |
| Request for single measuring. |
| Response: |
| 2AH, 61H, 00H, 15H, 31H, 02H, 00H, 01H, 80H, 15H, F3H, 02H, 80H, 00H, 00H, 03H, 80H, 22H, 7BH, 04H, 88H, 28H, 2BH, 22H, 0DH |
| <p>Meaning of items is described in highlighted part. Highlighted are: Status and then alternately single channels in different hue of grey.</p> <p>00H – command received OK</p> <p><i>Chanel 1 with value 5619:</i> 01H – byte <i>chn</i> with number of channel 1 80H – <i>status</i> of measured value for channel 1. Value is valid and in range. 15H,F3H – measured value from channel 1 as a 16-bit number between 0 to 10000</p> <p><i>Chanel 2 with value 0:</i> 02H – byte <i>chn</i> with number of channel 2 80H – <i>status</i> of measured value for channel 2. Value is valid and in range. 00H,00H – measured value from channel 2 as a 16-bit number between 0 to 10000</p> <p><i>Chanel 3 with value 8827:</i> 03H – byte <i>chn</i> with number of channel 3 80H – <i>status</i> of measured value for channel 3. Value is valid and in range. 22H,7BH – measured value from channel 3 as a 16-bit number between 0 to 10000</p> <p><i>Chanel 4 with value above the upper limit (value 10283):</i> 04H – byte <i>chn</i> with number of channel 4 88H – <i>status</i> of measured value for channel 4. Value is valid and is above upper limit. 28H,2BH – measured value from channel 3 as a 16-bit number.</p> |

In 66 Format:

Request: „MR0“ (*Measure Read*)

Response: (ACK „0“)(ch1)(stat1)(val1)...(ch4)(stat4)(val4)

- Legend:
- (chX) 2 characters; character break and number of channel; „1“ for first channel, „2“ for second channel, etc.
 - (statX) 3 character; character break and two characters as a status of measured-out value:
 - 80 ... measured-out value is valid
 - 88 ... value exceeded the upper limit of measuring range.
 - (valX) 2 through 6 characters; character break and measured-out value rounded off three digits. Rounding off is adjustable by instruction Conversion and Display Setup on page 40.

Example: Request

*B1MR0↵

Response – channel 1: valid value 806.00; channel 2: valid value 0.00; channel 3: value exceeded the upper limit; channel 3: valid value 1874.50; rounding off set to two digits.

*B10 1 80 809.00 2 80 0.00 3 88 655.47 4 80 1874.50↵

Continuous Measuring – start

Continuous measuring is a function by means of which AD4 performs measurements in set intervals and sends the measured values automatically via the communication line.

This instruction runs continuous measuring from all channel in the set intervals. Depending on the setup, the measured values are converted to decimal numbers or sent without conversion as numbers ranging from 0 to 10000. The number of measurements can be limited to a certain number or it is possible to continue in measuring until End of measuring instruction has been activated.

It is not recommended to communicate with the module when the automatical sending of values is in operation (with the exception of End of measuring instruction).

Request:

Instruction Code: 52H

Parameters: [interval][sample_counter][flags]

Not all the aforesaid parameters must be present and it is not necessary to adhere to the sequence specified above either. Each parameter shall be preceded by a parameter code shown in the following description as *id*. The parameters shall thus be entered in the following structure (id_ofparameterA)(parameterA)(id_ofparameterB)(parameterB), etc. The last setting shall be used for parameters that have not been introduced, or default setting shall be used (if they have not been entered yet).

| | |
|--|----------------------------|
| interval Setting the period of continuous measuring | length: 2 bytes id: 01H |
| Interval sets the period of sending automated response containing measured-out value. Measuring period comes up from this relation: $\text{period} = \text{interval} \times 406 \text{ ms}$ Value 0 is not an option. Therefore it is possible to set the period from 406 ms to 7.5 hours. Bytes are in order MSB:LSB. Default value is 406 ms. | |
| sample_counter Number of samples | length: 2 bytes id: 02H |
| This parameter sets the number of samples that are to be measured. If the value of this parameter equals zero (0), measuring continues indefinitely until the End of measuring instruction is received. Bytes are in order MSB:LSB. Default value: 0 | |

| | |
|--|--|
| flags | length: 1 byte |
| Other parameters | id: 03H |
| Some other parameters are determined in this byte. | |
| Default value: 00H | |
| bit 0 (LSb) | <i>Non conversion measuring</i> 0 = values transmitted during continuous measuring are from interval 0 to 10000. |
| | <i>Measuring and conversion</i> 1 = values transmitted during continuous measuring are converted according to the actual setting. See page 40 for Conversion and Display Setup. |

Response:

Acknowledge code: ACK 00H

Automated responses:

Automated responses are transmitted according to parameters set above. As the first and the last is transmitted packet containing byte *frame_identifier*. Between these two packets the measured-out values are transmitted (all channels at once).

Parameters of the first and the last packet: (frame_identifier)

Parameters of the packet of measuring: {(chn₁)(status₁)(value₁)} {...} {...} {(chn₄)(status₄)(value₄)}

| | | |
|---|---|----------------|
| frame_identifier | Status of starting/ending automated response | length: 1 byte |
| Is byte that is present in the first and the last packet of automated responses. It determines whether the packet is starting or ending. Also reason of the end of measuring can be identified from it. | | |
| bit 0 (LSb) | 0 = end of measuring | |
| | 1 = start of measuring | |
| bit 2 | 0 = measuring terminated manually using the instruction stop | |
| | 1 = measuring terminated after specified samples are measured-out. (termination by parameter <i>sample_counter</i>) | |

| | | |
|--|----------------|----------------|
| chn | Channel number | length: 1 byte |
| This byte designates channel number and it holds for all following bytes until next <i>chn</i> byte. In essence that means that following bytes (status, value) attach to channel with designated number. It ranges from 01H to 04H according to channel number. | | |

| | | |
|---|---|----------------|
| status | Status of the measured-out value | length: 1 byte |
| Status of measured-out value for the channel with the number stated in <i>chn</i> byte. | | |
| bit 2 | 0 = value is in measuring range | |
| | 1 = value is above upper limit (overflow) | |
| bit 7 (MSb) | 0 = invalid value | |
| | 1 = valid value | |

| value | Measured-out value |
|--|--------------------|
| Measured value from the channel with number stated in previous byte <i>chn</i> . Length differs according to settings of continuous measuring in <i>flags</i> byte. | |
| <i>Non conversion measuring</i> | length: 2 bytes |
| 16-bit number from range 0 – 10 000. Bytes are in order MSB:LSB. | |
| <i>Measuring and conversion</i> | length: 14 bytes |
| In this case values are transmitted in two formats simultaneously. In 32-bit float format according to the IEEE 754 ⁴ and in ASCII as ten characters of decimal number. Values are in following order: <i>Example:</i> Value 9215,85 is formulated as: 46H, 0FH, FFH, 66H, 20H, 20H, 20H, 39H, 32H, 31H, 35H, 2EH, 38H, 35H IEEE 754 part: 46H, 0FH, FFH, 66H ASCII part: 20H, 20H, 20H, 39H, 32H, 31H, 35H, 2EH, 38H, 35H (9215.85) | |

⁴ Description of IEEE 754 is available here: http://en.wikipedia.org/wiki/IEEE_754

Examples:

| |
|---|
| Request: |
| 2AH, 61H, 00H, 05H, 31H, 02H, 52H, EAH, 0DH |
| Here is an example of Measurement with no entered parameters. Only instruction code 52H is stated. For parameters are used last previously entered parameters. In case the parameters have never been entered, default parameters are used. |
| Response: |
| 2AH, 61H, 00H, 05H, 31H, 02H, 00H, 3CH, 0DH |
| Receiving the command for start of measuring has been confirmed. |
| First automatic response (start of measuring): |
| 2AH, 61H, 00H, 06H, 31H, 00H, 0EH, 01H, 2EH, 0DH |
| First automatic response contains identification 0EH and byte <i>frame_identifier</i> – value 01H means start of measuring. |
| Last automatic response (end of measuring): |
| 2AH, 61H, 00H, 06H, 31H, 33H, 0EH, 04H, F8H, 0DH |
| Last automatic response contains identification 0EH and byte <i>frame_identifier</i> – value 04H means end of measuring after previously set number of measurements. |
| One of automatic responses with measured-out values – no conversion measuring. |
| 2AH, 61H, 00H, 15H, 31H, 52H, 0EH, 01H, 80H, 15H, F3H, 02H, 80H, 00H, 00H, 03H, 80H, 22H, 7BH, 04H, 88H, 28H, 2BH, C4H, 0DH |
| 2AH, 61H, 00H, 15H, 31H, 01H, 0EH, 01H, 80H, 15H, F3H, 02H, 80H, 00H, 00H, 03H, 80H, 28H, 2BH, 04H, 88H, FFH, FFH, B4H, 0DH |
| The meaning of particular items in highlighted part. Highlighted are status and alternately particular channels in various shade of grey. |
| 0EH – Automatic response identification |
| <i>Channel 1 with value 5619:</i> |
| 01H – byte <i>chn</i> and channel number 1 |
| 80H – <i>status</i> of measured-out value for channel 1. Value is valid and in range. |
| 15H, F3H – measured-out value from channel 1 as a 16 bit number from interval 0 to 10000 |
| <i>Channel 2 with value 0:</i> |
| 02H – byte <i>chn</i> and channel number 2 |
| 80H – <i>status</i> of measured-out value for channel 2. Value is valid and in range. |
| 00H, 00H – measured-out value from channel 1 as a 16 bit number from interval 0 to 10000 |
| <i>Channel 3 with value 8827:</i> |
| 03H – byte <i>chn</i> and channel number 3 |
| 80H – <i>status</i> of measured-out value for channel 3. Value is valid and in range. |
| 22H, 7BH – measured-out value from channel 1 as a 16 bit number from interval 0 to 10000 |
| <i>Channel 4 with exceeded limit of range (value 10283):</i> |
| 03H – byte <i>chn</i> and channel number 4 |
| 88H – <i>status</i> of measured-out value for channel 4. Value is valid but above upper limit of range. |
| 28H, 2BH – measured-out value from channel 1 as a 16 bit number from interval 0 to 10000 |

One of automatic responses with measured-out values – measuring and conversion.

```
2AH, 61H, 00H, 45H, 31H, 08H, 0EH, 01H, 80H, 40H, 96H, A7H, F0H, 20H, 20H, 20H, 20H, 20H, 20H,
34H, 2EH, 37H, 31H, 02H, 80H, C1H, 98H, C2H, 8CH, 20H, 20H, 20H, 2DH, 31H, 39H, 2EH, 30H, 39
H, 35H, 03H, 80H, 00H, 00H, 00H, 00H, 20H, 20H, 20H, 20H, 20H, 30H, 2EH, 30H, 30H, 30H, 04H, 8
0H, 00H, 00H, 00H, 00H, 20H, 20H, 20H, 20H, 20H, 30H, 2EH, 30H, 30H, 30H, 61H, 0DH
```

The meaning of particular items in highlighted part. Highlighted are status and alternately particular channels in various shade of grey.

0EH – Automatic response identification

Channel 1 with value 4.71:

01H – byte *chn* and channel number 1

80H – *status* of measured-out value for channel 1. Value is valid and in range.

40H,96H,A7H,F0H – measured-out value from channel 1 in float format

20H,20H,20H,20H,20H,20H,34H,2EH,37H,31H – measured-out value from channel 1 in ASCII

Channel 2 with value -19.095:

02H – byte *chn* and channel number 2

80H – *status* of measured-out value for channel 2. Value is valid and in range.

C1H,98H,C2H,8CH – measured-out value from channel 2 in float format

20H,20H,20H,2DH,31H,39H,2EH,30H,39H,35H – measured-out value from channel 1 in ASCII

Channel 3 with value 0.000.

Channel 4 with value 0.000.

Note: Description of SIG instruction is automatically incremented in automatic responses.

In format 66:

Request: „MC“(interval)

Response: (ACK „0“)

Automatic Response: (ACK „E“)(value)

Legend: (interval) 1 through 5 characters; Send interval of automatic response with measured-out value. Period of measuring is given by relation: (interval) * 406 [ms]. Therefore it is possible to set time from 406 ms to approximately 7 hours and 23.5 minutes. Default value is 406 ms. If it is set to 0, measuring will terminate.

Example: Request

```
*B1MC1↵
```

Response

```
*B10↵
```

Automatic responses – channel 1: valid value 4.71; channel 2: valid value -19.095; channel 3: valid value 0.000; channel 4: valid value 0.000:

```
*B1E 1 80 4.71 2 80 -19.095 3 80 0.000 4 80 0.000↵
```

End of measuring

Continuous measuring is a function by means of which AD4 performs measurements in set intervals and sends the measured-out values automatically via the communication line.

This instruction deactivates the ongoing continuous measuring. This way it is possible to terminate continuous measuring which has been initiated without limiting the number of samples as well as continuous measuring which has not yet measured the required number of samples.

Request:

Instruction code: 53H

Response:

Acknowledge code: ACK 00H

Examples:

| |
|---|
| Request: |
| 2AH, 61H, 00H, 05H, 01H, 02H, 53H, 19H, 0DH |
| End of measuring. |
| Response: |
| 2AH, 61H, 00H, 05H, 01H, 02H, 00H, 6CH, 0DH |
| Command receiving confirmed. |

66 format:

The measuring is stopped by command MC0 in 66 format – see format 66, instruction “Continuous Measuring – start”.

Continuous Measuring Setup

Continuous measuring is a function by means of which AD4 performs measurements in set intervals and sends the measured values automatically via the communication line.

This instruction can be used to set the parameters of continuous measuring independently of the start of the measuring. This instruction can be used only when continuous measuring is not in operation.

Request:

Instruction code: 54H

Parameters: (interval) (sample_counter) (flags)

(Parameters are the same as for instruction „Continuous Measuring – start“ on the page 13.)

Response:

Acknowledge code: ACK 00H

Examples:

| |
|---|
| Request: |
| 2AH, 61H, 00H, 0BH, 31H, 02H, 54H, 01H, 00H, 05H, 02H, 00H, 32H, A8H, 0DH |
| Meaning of particular highlighted items: 54H – instruction code 01H – <i>interval</i> parameter ID 00H,05H – measuring interval 2.03 seconds (5 x 406 ms) 02H – <i>sample_counter</i> parameter ID 00H,32H – parameter <i>sample_counter</i> with value 32H, that gives 50 measurings |

Reading settings of continuous measuring

This instruction allows us to read the parameters set by previous instruction.

Request:

Instruction code: 55H

Response:

Acknowledge code: ACK 00H

Parameters: (interval) (sample_counter) (flags)

(Parameters are the same as for instruction „Continuous Measuring – start“ on the page 13.)

Examples:

| |
|---|
| Request: |
| 2AH, 61H, 00H, 05H, 31H, 02H, 55H, E7H, 0DH |
| Command for reading parameters of continuous measuring. |
| Response: |
| 2AH, 61H, 00H, 0BH, 31H, 02H, 00H, 01H, 00H, 05H, 02H, 00H, 32H, FCH, 0DH |
| Meaning of particular highlighted items: 00H – acknowledge code 01H – <i>interval</i> parameter ID 00H,05H – measuring interval 2,03 seconds (5 x 406 ms) 02H – <i>sample_counter</i> parameter ID 00H,32H – parameter <i>sample_counter</i> with value 32H, that gives 50 measurements |

Communication line and address settings

Configuration Permission

This instruction enables configurations to be carried out. It must immediately precede some instructions for communication parameters setup. After a following instruction (even an invalid one) the configuration is automatically disabled again.

This instruction cannot be used with the universal address. There must always be entered an address of a particular device.

Request:

Instruction code: E4H

Response:

Acknowledge code: ACK 00H

Examples:

| |
|---|
| Request: |
| 2AH, 61H, 00H, 05H, 01H, 02H, E4H, 88H, 0DH |
| Configuration permission. |
| Response: |
| 2AH, 61H, 00H, 05H, 01H, 02H, 00H, 6CH, 0DH |
| Command receiving confirmed. |

In 66 format:

Request: „E“ (Enable)

Response: (ACK „0“)

Example: Request

**B1E↵*

Response

**B10↵*

Communication Parameters Setup

This instruction set the address in Spinel protocol and the communication speed. It is not possible to use the universal address in this instruction.

In case the address is not known and no other device is connected on the line, the address can be found out using the instruction of "Communication Parameters Reading". (Use the universal FEH address as the device address.) If this is not possible (there are other devices on the same communication line), you can assign an address to the required device by using the instruction of "Address Setup using Serial Number " (page 24).

The setup of communication parameters must be preceded by the instruction for "Configuration Permission" (page 20).

Request:

Instruction code: E0H

Parameters: (address) (speed)

| address | New address of the device | length: 1 byte |
|--|---------------------------|----------------|
| New address of the device in Spinel protocol. Address ranges from 00H to FDH. If the device uses 66 format, it is necessary to use only addresses from ASCII range (see Address part on page 7.) Default address: 31H | | |

| speed | New communication speed | length: 1 byte | | |
|---|-------------------------|----------------|----------------|--|
| This parameter sets new communication speed of the device. Speed is unchangeable in AD4ETH and AD4USB devices and it is set to 115 200 Bd. Default communication speed in AD4RS is 9 600 Bd. Codes of communication speeds are in table on the right side: | Speed [Bd] | Format 97 code | Format 66 code | |
| | 110 | 00H | 0 | |
| | 300 | 01H | 1 | |
| | 600 | 02H | 2 | |
| | 1 200 | 03H | 3 | |
| | 2 400 | 04H | 4 | |
| | 4 800 | 05H | 5 | |
| | 9 600 | 06H | 6 | |
| | 19 200 | 07H | 7 | |
| | 38 400 | 08H | 8 | |
| | 57 600 | 09H | 9 | |
| | 115 200 | 0AH | A | |
| | 230 400 | 0BH | B | |

Response:

Acknowledge code: ACK 00H

New address and communication speed is set after sending the response.

Examples:

| |
|--|
| Request: |
| 2AH, 61H, 00H, 07H, 01H, 02H, E0H, 02H, 0AH, 7EH, 0D |
| Address set to 02H and speed to 115200 Bd. |
| Response: |
| 2AH, 61H, 00H, 05H, 01H, 02H, 00H, 6CH, 0DH |
| New address and communication speed is set after sending the response. |

In 66 format:

Request: „AS“(address)⁵ (Address Set)

Response: (ACK „0“)

Legend: (address) see part Address on page 8.

Example: Request: Address 4

**B1AS4↵*

Response

**B10↵*

Request: „SS“(code)⁵ (Speed Set)

Response: (ACK „0“)

Legend: (code) Communication speed code according to the table on the previous page.

Example: Request: Speed 19200Bd (code 7)

**B1SS7↵*

Response

**B10↵*

⁵ Address and communication speed has to be set by two separate commands in format 66. (In format 97 this can be done in one instruction.)

Communication Parameters Reading

This instruction is designed for the detection of the set address of a required device in case it is unknown. The enquiry is sent to the FEH universal address. If even the communication speed is not known, it is necessary to try out all communication speeds available for the particular device. However, no other device can be connected on the line when finding out the required device address using the universal address.

Request:

Instruction code: F0H

Response:

Acknowledge code: ACK 00H

Parameters: (address) (speed)

| address | Device's address | length: 1 byte |
|--------------------------------------|------------------|----------------|
| Device's address in Spinel protocol. | | |

| speed | Communication speed | length: 1 byte | |
|---|---------------------|----------------|----------------|
| Communication speed code. | Speed [Bd] | Format 97 code | Format 66 code |
| Speed is unchangeable in AD4ETH and AD4USB devices and it is set to 115 200 Bd. | 110 | 00H | 0 |
| | 300 | 01H | 1 |
| Default communication speed in AD4RS is 9 600 Bd. | 600 | 02H | 2 |
| | 1 200 | 03H | 3 |
| | 2 400 | 04H | 4 |
| | 4 800 | 05H | 5 |
| Codes of communication speeds are in table on the right side: | 9 600 | 06H | 6 |
| | 19 200 | 07H | 7 |
| | 38 400 | 08H | 8 |
| | 57 600 | 09H | 9 |
| | 115 200 | 0AH | A |
| | 230 400 | 0BH | B |

Examples:

| |
|---|
| Request: |
| 2AH, 61H, 00H, 05H, FEH, 02H, F0H, 7FH, 0DH |
| Communication parameters reading using universal address FEH. |
| Response: |
| 2AH, 61H, 00H, 07H, 04H, 02H, 00H, 04H, 06H, 5DH, 0DH |
| Address 04H, communication speed 9600 Bd. |

In 66 format:

Request: „CP“ (Communication Parameter)

Response: (ACK „0“)(address)(speed)

Legend: (address) see part Address on page 8.

(speed) Communication speed code according to the table for speed parameter.

*Example: Request with universal address: *\$1CP↵*

*Response – Address B, speed 9600Bd (code 6): *B10B6↵*

Address Setup using Serial Number

This instruction enables the user to set the address based on the unique serial number of the device. This instruction is handy when the superior system or operating staff lose the address of a device which is on the same communication line with other devices.

The serial number is shown on the product in the following structure *[product-numbr].[hardware-version].[software-version]/[serial-number]* for example like this: *0227.00.03/0001*

Request:

Instruction code: EBH

Parameters: (new_address)(product_number)(serial_number)

| | | |
|--|---------------------------|----------------|
| new_address | New address of the device | length: 1 byte |
| New device's address in Spinel protocol. | | |

| | | |
|--|----------------|-----------------|
| product_number | Product number | length: 2 bytes |
| Product number is stated on the label. For the device with 0227.00.03/0001 on the label, 227 is product number. | | |

| | | |
|---|------------------------------|-----------------|
| serial_number | Serial number of the product | length: 2 bytes |
| Serial number is stated on the label. For the device with 0227.00.03/0001 on the label, 1 is product number. This number can be read by instruction „Manufacturer data reading“ (see page 29). | | |

Response:

Acknowledge code: ACK 00H

Examples:

| |
|---|
| Request: |
| 2AH, 61H, 00H, 0AH, FEH, 02H, EBH, 32H, 00H, C7H, 00H, 65H, 21H, 0DH |
| New address 32H, product number 199 (= 00C7H), serial number 101 (= 0065H). |
| Response: |
| 2AH, 61H, 00H, 05H, 32H, 02H, 00H, 3BH, 0DH |
| Address has been changed – device responses with <u>new address</u> . |

Calibration

It is not necessary to calibrate the device before use. It has been calibrated in the factory based on the requirements specified in the order.

Calibration procedure:

By improper modification of calibration constants you can deteriorate the functioning of the device. The calibration shall be only carried out using devices with at least one-level higher accuracy compared to AD4xxx!

- 1) On the calibrated input bring the **H** value close to the **R** input range.
- 2) Carry out several measurements (for example 5) and calculate the average. The resulting value is **Mh**.
- 3) Convert **Mh** to the whole range:

$$M = Mh \times \frac{R}{H}$$

- 4) Calculate the constant **K**:

$$K = D \times \frac{65536}{M}$$

- 5) Write **K** constant into AD4xxx and verify the correctness by measuring.

Calibration constants writing

Instruction writes calibration constants. It is possible to write one through four constants at once.

Request:

Instruction code: 12H

Parameters: (channel)(constant)

| | | |
|-----------------------------------|-------------------|----------------|
| channel | Number of channel | length: 1 byte |
| Channel number from range 1 to 4. | | |

| | | |
|---|----------------------|-----------------|
| constant | Calibration constant | length: 2 bytes |
| Calibration constant. Bytes are entered in order MSB:LSB. | | |

Response:

Acknowledge code: ACK 00H

Reading of calibration constants

Instruction reads calibration constants including the data about how many divisions are for minimal and maximal limits.

Request:

Instruction code: 13H

Response:

Acknowledge code: ACK 00H

Parameters: (constant)(min)(max)

| constant | Calibration constant | length: 2 bytes |
|--|----------------------|-----------------|
| Calibration constant. Two bytes in order MSB:LSB | | |

| min | Minimal value | length: 2 bytes |
|--|---------------|-----------------|
| States how many divisions matches minimal value. 16bit value with sign. Typically 0. | | |

| max | Maximal value | length: 2 bytes |
|---|---------------|-----------------|
| States how many divisions matches maximal value. 16bit value with sign. Typically 10 000. | | |

Measurement type setting

Sets the way of conversion for measured values. Available are voltage, current and current range from 4 to 20 mA.

Request:

Instruction code: 1AH

Parameters: (channel)(type)

| channel | Channel number | length: 1 byte |
|----------------------------|----------------|----------------|
| Chanel number from 1 to 4. | | |

| typ | Measuring type | length: 1 byte |
|---|----------------|----------------|
| 00H for standard conversion – voltage ranges 01H for current range from 4 to 20 mA 02H for standard conversion – other current ranges | | |

Response:

Acknowledge code: ACK 00H

Reading of measurement type settings

Finds out what type of measuring is set. It can be voltage, current or special current from 4 to 20 mA.

Request:

Instruction code: 1BH

Response:

Acknowledge code: ACK 00H

Parameters: (typ)

| Type | Measurement type | length: 1 byte |
|------|--|----------------|
| 00H | for standard conversion – voltage ranges | |
| 01H | for current range from 4 to 20 mA | |
| 02H | for standard conversion – other current ranges | |

RAW measurement

Reads the last measured values from all the channels of the converter. The value measured directly by the internal A/D converter is sent without any subsequent calculation. This instruction facilitates the procedure of calibration and synchronization. When the device is in operation, it is more suitable to use the instruction for “Single measuring“ as described on page 11.

Request:

Instruction code: 5FH

Parameters: (const)

| const | constant | length: 1 byte |
|---------------|---|----------------|
| Constant 00H. | This byte ensures compatibility with other devices and allows further features installed. | |

Response:

Acknowledge code: ACK 00H

Parameters: {(chn₁)(status₁)(value₁)} {...} {...} {(chn₄)(status₄)(value₄)}

| chn | Channel number | length: 1 byte |
|--|----------------|----------------|
| This byte designates channel number and it holds for all following bytes until next <i>chn</i> byte. In essence that means that following bytes (status, value) attach to channel with designated number. It ranges from 01H to 04H according to channel number. | | |

| status | Status of the measured-out value | length: 1 byte |
|---|--|----------------|
| Status of measured-out value for the channel with the number stated in <i>chn</i> byte. | | |
| bit 3 | 0 = value is in measuring range 1 = value is above upper limit (overflow) | |
| bit 7 (MSb) | 0 = invalid value 1 = valid value | |

| value | Measured-out value | length: 2 bytes |
|---|--------------------|-----------------|
| Measured value from the channel with number stated in previous byte <i>chn</i> . 16-bit measured-out value. Bytes are in order MSB;LSB. | | |

Additional

Name and version reading

Reads name of the device, version of inner software and list of possible communication formats. Set by manufacturer.

Request:

Instruction code: F3H

Response:

Acknowledge code: ACK 00H

Parameters: (string)

| string | Name and version | length: 1 byte |
|--|------------------|----------------|
| One of following texts according to the type of device: AD4ETH; v0293.01.04; f66 97 AD4USB; v0295.01.04; f66 97 AD4RS; v0294.01.04; f66 97 | | |
| There can also be other information in the string. Such information's are separated by semicolon and break. Lower case character states the type of information. | | |
| <i>Example:</i> AD4ETH; v0293.01.04; f66 97; t1; s358; dDG21 | | |

Examples:

| |
|--|
| Request: |
| 2AH, 61H, 00H, 05H, FEH, 02H, F3H, 7CH, 0DH |
| Command for reading of name and version. |
| Response: |
| 2AH, 61H, 00H, 20H, 31H, 02H, 00H, 41H, 44H, 34H, 45H, 54H, 48H, 3BH, 20H, 76H, 30H, 32H, 39H, 33H, 2EH, 30H, 31H, 2EH, 30H, 32H, 3BH, 20H, 66H, 36H, 36H, 20H, 39H, 37H, 0CH, 0DH |
| Example of device's response: AD4ETH (AD4ETH; v0293.01.02; f66 97). |

In 66 format:

Request: „?“

Response: (ACK „0“)

Example: Request

**B1?↵*

Response:

**B10 AD4 ETH; V0293.01.02; F66 97↵*

Note: There can also be other information in the instruction. Such informations are separated by semicolon and break. Lower case character states the type of information.

(Example: AD4ETH; v0293.01.02; f66 97; t1; s358; dDG21)

Manufacturer data reading

Instruction reads the data set by manufacturer.

Request:

Instruction code: FAH

Response:

Acknowledge code: ACK 00H

Parameters: (product_number)(serial_number)(other)

| | |
|---|-----------------|
| product_number | length: 2 bytes |
| Product number. For the device with 0227.00.03/0001 on the label, 227 is product number. | |
| serial_number | length: 2 bytes |
| Device's serial number. For the device with 0227.00.03/0001 on the label, 1 is serial number. | |
| other | length: 4 bytes |
| Other Manufacturer data. | |

Examples:

| |
|---|
| Request: |
| 2AH, 61H, 00H, 05H, FEH, 02H, FAH, 75H, 0DH |
| Response: |
| 2AH, 61H, 00H, 0DH, 35H, 02H, 00H, 00H, C7H, 00H, 65H, 20H, 05H, 09H, 23H, B3H, 0DH |
| Product number is 199 (= 00C7H) and serial number is 101 (= 0065H). |

User Data Saving

The instruction saves the required user data into relevant memory. The device will remember data saved in user data memory even after power supply failure or reset. This memory space is suitable for example for the specification of the device's location etc.

Request:

Instruction code: E2H

Parameters: (position)(data)

| | |
|--|----------------|
| position | length: 1 byte |
| Address of position in memory where the entered data will be saved. Ranges from 00H to 0FH. | |

| | |
|--|-----------------------|
| data | length: 1 to 16 bytes |
| Any user data. Memory has a capacity of 16 bytes, if the first entry is saved in first position. In case there is not enough space in memory for the user data, the device answers with error and writes nothing. (For example if you try to write to memory address 0CH, you can only write 4 bytes max.) | |

Response:

Acknowledge code: ACK 00H

Examples:

| |
|---|
| Request: |
| 2AH, 61H, 00H, 0FH, 31H, 02H, E2H, 00H, 53H, 74H, 6FH, 72H, 61H, 67H, 65H, 20H, 41H, 1AH, 0DH |
| Writing of string <i>Storage A</i> (53H, 74H, 6FH, 72H, 61H, 67H, 65H, 20H, 41H). |
| Response: |
| 2AH, 61H, 00H, 05H, 31H, 02H, 00H, 3CH, 0DH |
| String has been written. |

In 66 format:

Request: „DW“(position)(data) *(Data Write)*

Response: (ACK „0“)

Legend: (position) Address of position in memory where the entered data will be saved.
Ranges from 0-9 or A-F.

(data) 1 through 16 bytes; Any user data. From interval 0-9 or A-F.

Example: Request

**B1DW0STORAGE A↵*

Response

**B10↵*

Saved User Data Reading

This instruction reads the data saved in the user data memory. The device will remember data saved into this memory even after power supply failure or reset. This memory space is suitable for example for the specification of measuring points.

Request:

Instruction code: F2H

Response:

Acknowledge code: ACK 00H

Parameters: (data)

| | |
|-------------|------------------|
| data | length: 16 bytes |
| User data. | |

Example:

| |
|---|
| Request: |
| 2AH, 61H, 00H, 05H, 31H, 02H, F2H, 4AH, 0DH |
| Response: |
| 2AH, 61H, 00H, 15H, 31H, 02H, 00H, 53H, 74H, 6FH, 72H, 61H, 67H, 65H, 20H, 41H, 20H, 20H, 20H, 20H, 20H, 20H, 20H, 16H, 0DH |
| There is a string „Storage A“ saved in user data. |

In 66 format:

Request: „DR“ (Data Read)

Response: (ACK „0“)(data)

Legend: (data) 1 through 16 bytes; User data.

Example: Request

*B1DR↵

Response

*B10STORAGE A↵

Input Name Saving

Enables the user to save a unique character string for each input. This function is suitable for the specification of individual inputs.

This memory space uses the control software and is also used in AD4ETH for input names saving. For these reasons we do not recommend manipulating with this memory space AD4.

Request:

Instruction code: 2BH

Parameters: (input)(data)

| | |
|--|------------------|
| input | length: 1 byte |
| Number of input (channel) from 01H to 04H. | |
| data | length: 21 bytes |
| Any user data. | |

Response:

Acknowledge code: ACK 00H

Examples:

| |
|---|
| Request: |
| 2AH, 61H, 00H, 1BH, 31H, 02H, 2BH, 01H, 30H, 4BH, 6FH, 74H, 65H, 6CH, 6EH, 61H, 00H, 00H, 00H, 00H, 00H, 00H, 00H, 00H, 00H, 00H, 00H, 00H, 00H, FCH, 0DH |
| Writing of title "0Storage" for input 1 (unused bytes are filled by zeros "0"). |
| Response: |
| 2AH, 61H, 00H, 05H, 31H, 02H, 00H, 3CH, 0DH |
| String has been written. |

Reading of input title

Read input title.

Request:

Instruction code: 3BH

Parameters: (input)

| | |
|--|----------------|
| input | length: 1 byte |
| Number of input (channel) from 01H to 04H. | |

Response:

Acknowledge code: ACK 00H

Parameters: (data)

| | |
|-----------------------------|-----------------|
| data | length: 21 byte |
| Data saved for given input. | |

Examples:

| |
|---|
| Request: |
| 2AH, 61H, 00H, 06H, 31H, 02H, 3BH, 01H, FFH, 0DH |
| Response: |
| 2AH, 61H, 00H, 1AH, 31H, 02H, 00H, 30H, 4BH, 6FH, 74H, 65H, 6CH, 6EH, 61H, 00H, 00H, 00H, 00H, 00H, 00H, 00H, 00H, 00H, 00H, 00H, 00H, 00H, 00H, 29H, 0DH |
| Saved string is "0Storage" (unused bytes are filled by zeros "0"). |

Status Setup

Sets the status of the device. User defined byte which can be used to find out the device status. It is possible for the user to enter this byte as requested. It serves as memory space suitable for example of user's own specification of device status. (Set to zero after reset or power supply restoration.)

Request:

Instruction code: E1H

Parameters: (status)

| | |
|--|----------------|
| status | length: 1 byte |
| Device's status. After turning the device on or reset (even software one) the device, default status 00H is set. If it is changed by instruction Status Setting, it is easily identifiable at any point. | |

Response:

Acknowledge code: ACK 00H

Examples:

| |
|--|
| Request: |
| 2AH, 61H, 00H, 06H, 01H, 02H, E1H, 12H, 78H, 0DH |
| Setting of status 12H. |
| Response: |
| 2AH, 61H, 00H, 05H, 01H, 02H, 00H, 6CH, 0DH |
| Acknowledge. |

In 66 format:

Request: „SW“(status) (Status Write)

Response: (ACK „0“)

Legend: (status) character frim interval „break“ to „~“ (32 – 126 in ASCII code)

Example: Request – character A

**B1SWA~*

Response

**B10*

Reading of status

Reads device's status. It is user defined byte, which can be used for finding out the device's status.

Request:

Instruction code: F1H

Response:

Acknowledge code: ACK 00H

Parameters: (status)

| | |
|---|----------------|
| status | length: 1 byte |
| Device's status. After turning the device on or reset (even software one) the device, default status 00H is set. | |

Examples:

| |
|--|
| Request: |
| 2AH, 61H, 00H, 05H, 01H, 02H, F1H, 7BH, 0DH |
| Response: |
| 2AH, 61H, 00H, 06H, 01H, 02H, 00H, 12H, 59H, 0DH |
| Device's status is set to 12H. |

In 66 format:

Request: „SR“ (Status Read)

Response: (ACK „0“)(character)

Legend: (character) character from interval „break“ to „~“ (32 – 126 in ASCII code)

Example: Request

*B1SR↵

Response

*B10A↵

Reading of communication errors

Instruction returns number of communication errors that occurred from the time when the device has been turned on, or from the time of last reading.

Request:

Instruction code: F4H

Response:

Acknowledge code: ACK 00H

Parameters: (errors)

| errors | length: 1 byte |
|--|----------------|
| Number of communication errors that occurred from the time when the device has been turned on, or from the time of last reading. Following events are considered as errors: <ul style="list-style-type: none"> • Prefix is expected, but another byte arrives instead. • Checksum SUMA does not match. • Message is incomplete. | |

Examples:

| |
|--|
| Request: |
| 2AH, 61H, 00H, 05H, 01H, 02H, F4H, 78H, 0DH |
| Response: |
| 2AH, 61H, 00H, 06H, 01H, 02H, 00H, 05H, 66H, 0DH |
| 5 errors occurred since the device has been turned on. |

Checksum Permission

This function enables the user to switch off the checkup of the checksum accuracy. This instruction is handy for the synchronization of applications. When entering instructions manually using a terminal, it is not necessary to accurately enter the checksum (the one but last byte).

We do not recommend you to switch the checkup off in other situations than in testing operation of the device. The checksum serves as a protection against data corruption during their transfer over the communication line. The checkup is switched on by default.

Request:

Instruction code: EEH

Parameters: (state)

| State | length: 1 byte |
|--|----------------|
| 00H for turning off the control of checksum. | |
| 01H for turning on the control of checksum. | |

Response:

Acknowledge code: ACK 00H

Examples:

| |
|--|
| Request: |
| 2AH, 61H, 00H, 06H, 01H, 02H, EEH, 01H, 7CH, 0DH |
| Control turned on. |
| Response: |
| 2AH, 61H, 00H, 05H, 01H, 02H, 00H, 6CH, 0DH |
| Command confirmed. |

Checksum – settings reading

Finds out current checksum control settings. (See the description of previous instruction „Checksum Permission“.)

Request:

Instruction code: FEH

Response:

Acknowledge code: ACK 00H

Parameters: (state)

| state | length: 1 byte |
|---------------------------|----------------|
| 00H checksum control off. | |
| 01H checksum control on. | |

Examples:

| |
|--|
| Request: |
| 2AH, 61H, 00H, 05H, 01H, 02H, FEH, 6EH, 0DH |
| Response: |
| 2AH, 61H, 00H, 06H, 01H, 02H, 00H, 01H, 6AH, 0DH |
| Checksum control on. |

Reset

Executes reset of the device. Device gets in the same state as if it was just turned on.

Request:

Instruction code: E3H

Response:

Acknowledge code: ACK 00H

Examples:

| |
|--|
| Request: |
| 2AH, 61H, 00H, 05H, 01H, 02H, E3H, 89H, 0DH |
| Response: |
| 2AH, 61H, 00H, 05H, 01H, 02H, 00H, 6CH, 0DH |
| Reset is executed after this response is sent. |

In 66 format:

Request: „RE“ (Reset)

Response: (ACK „0“)

*Example: Request: *B1RE↵*

*Response: *B10↵*

Note: Reset is executed after this response is sent.

Auxiliary Instructions

The following instructions have been added purposefully to support the WEB interface in the Ethernet version of AD4ETH. They can also be found in AD4USB and AD4RS. They are system instructions designed only for advanced users.

Single Measurement with Conversion

This instruction reads the last measured values from all or just some of the converter channels. It returns values converted into decimal numbers (32bit float according to IEEE 754), and into a string of ten characters including the decimal point.

Request:

Instruction code: 58H

Parameters: (chn)

| chn | Channel | length: 1 až 4 byte |
|-----|---|---------------------|
| | One through four numbers of channels that are to be red. If the value 00H is entered, all channels will be red. | |

Response:

Acknowledge code: ACK 00H

Parameters: {(chn₁)(status₁)(value₁)} {...} {...} {(chn₄)(status₄)(value₄)}

| chn | Channel number | length: 1 byte |
|-----|--|----------------|
| | This byte designates channel number and it holds for all following bytes until next <i>chn</i> byte. In essence that means that following bytes (status, value) attach to channel with designated number. It ranges from 01H to 04H according to channel number. | |

| status | Status of the measured-out value | length: 1 byte |
|-------------|---|----------------|
| | Status of measured-out value for the channel with the number stated in <i>chn</i> byte. | |
| bit 3 | 0 = value is in measuring range 1 = value is above upper limit (overflow) | |
| bit 7 (MSb) | 0 = invalid value 1 = valid value | |

| value | Measured-out value | length: 14 byte |
|-------|--|-----------------|
| | Measured value from the channel with number stated in previous byte <i>chn</i> . | |
| | Values are sent in three formats simultaneously. First is 16bit value from 0 to 10 000 (integer in order MSB:LSB). Next are two values converted for actual range according to actual settings. As a 32 bit float in complaint with IEEE 754 ⁶ and ASCII as ten characters of decimal number. Values are sent in described order. | |
| | <i>Example:</i> | |
| | Value 9215.85 is formulated as: | |
| | 0AH, 58H, 46H, 0FH, FFH, 66H, 20H, 20H, 20H, 39H, 32H, 31H, 35H, 2EH, 38H, 35H | |
| | Part INT: 0AH, 58H (2648) | |
| | Part IEEE 754: 46H, 0FH, FFH, 66H | |
| | Part ASCII: 20H, 20H, 20H, 39H, 32H, 31H, 35H, 2EH, 38H, 35H (9215.85) | |

⁶ Description of IEEE 754 is available here: http://en.wikipedia.org/wiki/IEEE_754

Examples:

| |
|--|
| Request: |
| 2AH, 61H, 00H, 06H, 31H, 02H, 58H, 02H, E1H, 0DH |
| Command for reading channel 2. |
| Response: |
| 2AH, 61H, 00H, 17H, 31H, 02H, 00H, 02H, 80H, 15H, 3AH, 41H, ADH, E3H, 53H, 20H, 20H, 20H, 20H, 20H, 32H, 31H, 2EH, 37H, 34H, 99H, 0DH |
| From channel 2 was measured value 21.74. Channel number: 02H Status: 80H Part INT: 15H, 3AH (5434) Part IEEE 754: 41H, ADH, E3H, 53H Part ASCII: 20H, 20H, 20H, 20H, 20H, 32H, 31H, 2EH, 37H, 34H (21.74) |

Conversion and Display Setup

This instruction enables the user to set simultaneously various values used for the WEB interface, namely the name of the channel, text description of the measuring range, text description of units, display setup, number of decimal positions for rounding as well as the additive and multiplicative constant for the equation of the line based on which the basic range of 0 to 10000 divisions shall be converted into the range set by the user.

Request:

Instruction code: 1EH

Parameters: {[channel][name][range][units][display][float][multi-f][multi-a][add-f][add-a][type]}{...}

| | |
|--|---------------------------|
| channel Channel number | length: 1 byte id: 01H |
| This byte designates channel number and it holds for all following bytes until next <i>channel</i> byte. In essence that means that following bytes (status, value) attach to channel with designated number. It ranges from 01H to 04H according to channel number. | |

| | |
|---|-----------------------------|
| name Channel name | length: 21 bytes id: 11H |
| Memory position for saving the channel label. It is the same string as from instruction "Input Name Saving" on page 32. | |

| | |
|---|-----------------------------|
| range Measuring range | length: 15 bytes id: 12H |
| Text string defining measured range. For example: „0 – 100 V“ | |

| | |
|--|----------------------------|
| units Set unit | length: 5 bytes id: 13H |
| Text string describing set units. For example: „V“, „A“, „pA“, „m“, etc. | |

| | |
|---|-----------------------------|
| display Parameters of display | length: 5 bytes id: 14H |
| Parameters of display of channel on the WEB page. (This variable is not yet used.) | |
| decimals Number of decimals | length: 1 byte id: 15H |
| Number of displayed rounded-off decimals. | |
| multi-f Multiplicative constant – float | length: 4 bytes id: 16H |
| <p>Multiplicative constant for conversion of measured-out value. Current value from converter is converted to decimal number according to this relation:</p> $result = multi \times measured + add$ <p>multi – <i>multi-f</i> represents multiplicative constant as float⁷ measured – measured-out value from A/D converter add – additive constant</p> <p><i>Note:</i> It is possible to enter either parameter multi-f or the parameter multi-a for single channel.</p> | |
| multi-a Multiplicative constant – ASCII | length: 10 bytes id: 17H |
| <p>Multiplicative constant for conversion of measured-out value. Current value from converter is converted to decimal number according to this relation:</p> $result = multi \times measured + add$ <p>multi – <i>multi-a</i> represents multiplicative constant as ASCII value. ASCII value is 10bytes including decimal point. measured – measured-out value from A/D converter add – additive constant</p> <p><i>Note:</i> It is possible to enter either parameter multi-f or the parameter multi-a for single channel.</p> | |
| add-f Additive constant – float | length: 4 bytes id: 18H |
| <p>Additive constant for conversion of measured-out value. Current value from converter is converted to decimal number according to this relation:</p> $result = multi \times measured + add$ <p>multi – multiplicative constant measured – measured-out value from A/D converter add – <i>add-f</i> represents multiplicative constant as float⁷</p> <p><i>Note:</i> It is possible to enter either parameter add-f or the parameter add-a for single channel.</p> | |

⁷ Description of IEEE 754 is available here: http://en.wikipedia.org/wiki/IEEE_754

| | |
|--|----------------------------|
| add-a Additive constant – ASCII | length: 10 byte id: 19H |
| <p>Multiplicative constant used for conversion of measured-out value. Current measured-out value from converter is converted to decimal number based on this relation:</p> $result = multi \times measured + add$ <p>multi – multiplicative constant measured – measured-out value from A/D converter add – <i>add-a</i> represents additive constant (add) entered as an ASCII value. ASCII value is 10 bytes aligned to the right including decimal point.</p> <p><i>Note:</i> It is possible to enter either parameter add-f or the parameter add-a for single channel.</p> | |

| | |
|--|---------------------------|
| typ Measurement type | length: 1 byte id: 20H |
| <p>Measurement type determines whether it is voltage range (00H), special current range (01H; 4 to 20 mA) or other current ranges (02H).</p> | |

Response:

Acknowledge code: ACK 00H

Examples:

| |
|--|
| Request: |
| <p>2AH, 61H, 00H, 15H, 31H, 02H, 1EH, 01H, 01H, 13H, 20H, 20H, 20H, B0H, 43H, 01H, 03H, 13H, 20H, 20H, 6BH, 50H, 61H, 33H, 0DH</p> |
| <p>Setting the range to °C for channel 1 and kPa for channel 3. Channel number (id 01H): 01H Units (id 13H): 20H, 20H, 20H, B0H, 43H (°C) Channel number (id 01H): 03H Units (id 13H): 20H, 20H, 6BH, 50H, 61H (kPa)</p> |
| Response: |
| <p>2AH, 61H, 00H, 05H, 31H, 02H, 00H, 3CH, 0DH</p> |
| <p>Command executed.</p> |

Conversion and Display Reading

This instruction read the setup of the name of the channel, text description of the measuring range, text description of units, display setup, number of decimal positions for rounding as well as the additive and multiplicative constant.

Request:

Instruction code: 1FH

Parameters: (channel)

| channel | Channel | length: 1 byte |
|---------|---|----------------|
| | Number of the channel that is to be read. | |

Response:

Acknowledge code: ACK 00H

Parameters: {[channel][name][range][units][display][decimals][multi-f][multi-a][add-f][add-a][type]}{...}

Description of the parameters is the same as for the previous instruction.

Examples:

| |
|---|
| Request: |
| 2AH, 61H, 00H, 06H, 31H, 02H, 1FH, 01H, 1BH, 0DH |
| Reading parameters for channel 1. |
| Response: |
| 2AH, 61H, 00H, 5DH, 31H, 02H, 00H, 01H, 01H, 11H, 20H, 53H, 74H, 75H, 64H, 6EH, 61H, 20H, 7AH, 61H, 20H, 68H, 75H, 6DH, 6EH, 79H, 20H, 20H, 20H, 20H, 20H, 12H, 20H, 20H, 20H, 20H, 20H, 2DH, 35H, 35H, 20H, 2BH, 31H, 35H, 30H, B0H, 43H, 13H, 20H, 20H, 20H, B0H, 43H, 14H, 41H, 42H, 43H, 44H, 45H, 15H, 02H, 16H, 3CH, B4H, 39H, 58H, 17H, 20H, 20H, 20H, 20H, 20H, 30H, 2EH, 30H, 32H, 32H, 18H, C2H, 5CH, 00H, 00H, 19H, 20H, 20H, 20H, 2DH, 35H, 35H, 2EH, 30H, 30H, 30H, 20H, 01H, F4H, 0DH |
| Channel 1 parameters are: |
| Channel number (id 01H): 01H |
| Name (id 11H): 20H, 53H, 74H, 75H, 64H, 6EH, 61H, 20H, 7AH, 61H, 20H, 68H, 75H, 6DH, 6EH, 79H, 20H, 20H, 20H, 20H, 20H (STORAGE) |
| Range (id 12H): 20H, 20H, 20H, 20H, 20H, 2DH, 35H, 35H, 20H, 2BH, 31H, 35H, 30H, B0H, 43H (-55 +150C) |
| Units (id 13H): 20H, 20H, 20H, B0H, 43H (°C) |
| Display parameters (id 14H): 41H, 42H, 43H, 44H, 45H |
| Number of decimals (id 15H): 02H |
| Multiplicative constant as float (id 16H): 3CH, B4H, 39H, 58H (0.022) |
| Multiplicative constant as ASCII (id 17H): 20H, 20H, 20H, 20H, 20H, 30H, 2EH, 30H, 32H, 32H (0,022) |
| Additive constant as float (id 18H): C2H, 5CH, 00H, 00H (-55) |
| Additive constant as ASCII (id 19H): 20H, 20H, 20H, 2DH, 35H, 35H, 2EH, 30H, 30H, 30H (-55) |
| Measurement type (id 20H): 01H (Current range from 4 to 20 mA) |

Values Monitoring Setup

This instruction enables the user to set for each channel an upper and lower limit to be monitored. Exceeding the upper limit or dropping below the lower limit will result in sending an automatic message to the superior system.

This instruction can also be used for setting the hysteresis of the set limits. The hysteresis applies below the upper limit and above the lower limit. The principle of hysteresis is described in Addition A – Hysteresis on page 51.

Depending on the setup, it is possible in AD4ETH to allow messages to be sent via the WEB interface in case these limits are violated. The WEB interface graphically signals any violation of the limits.

Request:

Instruction code: 1CH

Parameters: {[channel][attributes][lower-limit-f][lower-limit-a][upper-limit-f][upper-limit-a][hysteresis-f][hysteresis-a][error]}{...}

| | |
|--|---------------------------|
| channel Channel number | length: 1 byte id: 01H |
| This byte designates channel number and it holds for all following bytes until next <i>channel</i> byte. In essence that means that following bytes (status, value) attach to channel with designated number. It ranges from 01H to 04H according to channel number. | |

| | |
|---|---|
| attributes Other parameters | length: 1 byte id: 12H |
| Some other parameters are in this byte. Default value: 00H | |
| bit 7 (MSb) | 0 = Values monitoring off for this channel. 1 = Values monitoring on for this channel. |

| | |
|--|----------------------------|
| lower-limit-f Lower limit – float | length: 4 bytes id: 13H |
| Lower monitoring limit in float format. ⁸ <i>Note:</i> It is possible to enter either parameter lower-limit-f or the parameter lower-limit-a for single channel. | |

| | |
|--|-----------------------------|
| lower-limit-a Lower limit – ASCII | length: 10 bytes id: 14H |
| Lower monitoring limit in ASCII format. ASCII value is 10 bytes aligned to the right side including decimal point. <i>Note:</i> It is possible to enter either parameter lower-limit-f or the parameter lower-limit-a for single channel. | |

⁸ Popis normy IEEE 754 je k dispozici naExample zde: http://en.wikipedia.org/wiki/IEEE_754

| | |
|--|---|
| upper-limit-f Upper limit – float | length: 4 bytes id: 15H |
| Upper monitoring limit in float format. ⁸ <i>Note:</i> It is possible to enter either parameter upper-limit-f or the parameter upper-limit-a for single channel. | |
| Upper-limit-a Upper limit – ASCII | length: 10 bytes id: 16H |
| Upper monitoring limit in ASCII format. ASCII value is 10 bytes aligned to the right side including decimal point. <i>Note:</i> It is possible to enter either parameter upper-limit-f or the parameter upper-limit-a for single channel. | |
| hysteresis-f Hysteresis – float | length: 4 bytes id: 17H |
| Hysteresis in float format. ⁹ | |
| hysteresis-a Hysteresis – ASCII | length: 10 byte id: 18H |
| Hysteresis in ASCII format. ASCII value is 10 bytes aligned to the right side including decimal point. <i>Note:</i> It is possible to enter either parameter hysteresis-f or the parameter hysteresis-a for single channel. | |
| error Overflow behavior | length: 1 byte id: 1AH |
| This byte states what happens if A/D converter range overflow occurs. | |
| 00H | No information about overflow is sent. |
| 01H | Information about overflow is sent automatically. |

Response:

Acknowledge code: ACK 00H

⁹ Popis normy IEEE 754 je k dispozici naExample zde: http://en.wikipedia.org/wiki/IEEE_754

Automatic Response:

This response is generated in case there are set limits and they are violated or in case the measured value deviates from the physical range of the internal A/D converter.

Acknowledge code: ACK 0FH

Parameters: [event][channel][status][value]

| | |
|--|---------------------------|
| event Number of the event source | length: 1 byte id: 01H |
| This byte specifies the source of event. In case of exceeding limits or range, the automatic message can contain this byte to separate such errors. This byte's value is 30H. | |

| | |
|---|---------------------------|
| channel Channel number | length: 1 byte id: 02H |
| This byte designates the number of channel responsible for sending automatic instructions. It ranges from 01H to 04H according to channel number. | |

| | |
|---|---|
| status Measured-out value status | length: 1 byte id: 03H |
| Status of measured-out value for channel with channel number given in byte <i>channel</i> . | |
| bites 0 to 3 (lower nibble) | 0000 = measured-out value is in range |
| | 0001 = exceeding lower limit of measured range |
| | 0010 = exceeding upper limit of measured range |
| | 0100 = underflow of physical range of A/D converter (can occur only at 4 to 20 mA current range) |
| | 1000 = overflow of physical range of A/D converter |
| bit 7 (MSb) | 0 = measured-out value is invalid |
| | 1 = measured-out value is valid |

| | |
|---|----------------------------|
| value Measured-out value | length: 14 byte id: 04H |
| Measured value from the channel with number stated in previous byte <i>channel</i> . | |
| Values are sent in three formats simultaneously. First is 16bit value from 0 to 10 000 (integer in order MSB:LSB). Next are two values converted for actual range according to actual settings. As a 32 bit float in complaint with IEEE 754 ¹⁰ and ASCII as ten characters of decimal number. Values are sent in described order. | |
| <i>Example:</i> | |
| Value 9215,85 is formulated as: | |
| 0AH, 58H, 46H, 0FH, FFH, 66H, 20H, 20H, 20H, 39H, 32H, 31H, 35H, 2EH, 38H, 35H | |
| Part INT: 0AH, 58H (2648) | |
| Part IEEE 754: 46H, 0FH, FFH, 66H | |
| Part ASCII: 20H, 20H, 20H, 39H, 32H, 31H, 35H, 2EH, 38H, 35H (9215.85) | |

¹⁰ Description of IEEE 754 is available here: http://en.wikipedia.org/wiki/IEEE_754

Examples:

| |
|---|
| Request: |
| 2AH, 61H, 00H, 19H, 31H, 02H, 1CH, 01H, 01H, 12H, 80H, 14H, 20H, 20H, 20H, 20H, 32H, 35H, 2EH, 30H, 30H, 30H, 15H, 41H, A0H, 00H, 00H, C9H, 0DH |
| Setting the upper and lower limit for channel 1. Meaning of particular items: Channel number (id 01H): 01H Attributes (id 12H): 80H Upper limit as ASCII (id 14H): 20H, 20H, 20H, 20H, 32H, 35H, 2EH, 30H, 30H, 30H (25.000) Lower limit as float (id 15H): 41H, A0H, 00H, 00H (20.000) |
| Response: |
| 2AH, 61H, 00H, 05H, 31H, 02H, 00H, 3CH, 0DH |
| Command receiving confirmation. |
| Automatic response: |
| 2AH, 61H, 00H, 1CH, 31H, 13H, 0FH, 01H, 30H, 02H, 02H, 03H, 82H, 04H, 18H, BBH, 41H, CAH, 97H, 8CH, 20H, 20H, 20H, 20H, 20H, 32H, 35H, 2EH, 33H, 32H, ACH, 0DH |
| Automatic information about exceeding the upper limit 25.0 on channel 2. Current value is 25.23. Event number (id 01H): 30H Channel number (id 02H): 02H Attributes (id 03H): 82H Current value (id 04H): As INT: 18H, BBH as float: 41H, CAH, 97H, 8CH As ASCII: 20H, 20H, 20H, 20H, 20H, 32H, 35H, 2EH, 33H, 32H |

Reading the settings of values monitoring

This instruction allows us to read data written by previous instruction.

Request:

Instruction code: 1DH

Parameters: [channel]

Response:

Acknowledge code: ACK 00H

Parameters: {[channel][attributes][lower-limit-f][lower-limit-a][upper-limit-f][upper-limit-a][hysteresis-f][hysteresis-a][error]}{...}

Meaning of all parameters is stated in previous instruction description.

Examples:

| |
|---|
| Request: |
| 2AH, 61H, 00H, 06H, 31H, 02H, 1DH, 01H, 1DH, 0DH |
| Command for reading the parameters of monitoring values from channel 1. |
| Response: |
| 2AH, 61H, 00H, 3BH, 31H, 02H, 00H, 01H, 01H, 12H, 80H, 13H, 41H, C8H, 00H, 00H, 14H, 20H, 20H, 20H, 20H, 32H, 35H, 2EH, 30H, 30H, 30H, 15H, 41H, A0H, 00H, 00H, 16H, 20H, 20H, 20H, 20H, 32H, 30H, 2EH, 30H, 30H, 30H, 17H, 3EH, A6H, 66H, 66H, 18H, 20H, 20H, 20H, 20H, 20H, 30H, 2EH, 33H, 32H, 35H, 1AH, 00H, 60H, 0DH |
| <p>Meaning of highlighted items</p> <p>Channel number (id 01H): 01H</p> <p>Attributes (id 12H): 80H</p> <p>Upper limit as float (id 13H): 41H, C8H, 00H, 00H (25.000 – twenty-five point zero)</p> <p>Upper limit as ASCII (id 14H): 20H, 20H, 20H, 20H, 32H, 35H, 2EH, 30H, 30H, 30H</p> <p>Lower limit as float (id 15H): 41H, A0H, 00H, 00H (20.000)</p> <p>Lower limit as ASCII (id 16H): 20H, 20H, 20H, 20H, 32H, 30H, 2EH, 30H, 30H, 30H</p> <p>Hysteresis as float (id 17H): 3EH, A6H, 66H, 66H (0.325)</p> <p>Hysteresis as ASCII (id 18H): 20H, 20H, 20H, 20H, 20H, 30H, 2EH, 33H, 32H, 35H, 1AH, 00H</p> <p>Error (id 1AH): 00H</p> |

SWITCHING PROTOCOLS

Default communication protocol is Spinel. To switch the device to another protocol, following instructions are to be used. (You can use Spinel Terminal for example.)

Spinel → MODBUS RTU

Allow configuration

This instruction allows you to send the service instruction in the next step. This instruction has to precede the Switching instruction.

Instruction cannot be used with broadcast nor with universal address.

Request:

Instruction code: E4H

Response:

Instruction code: ACK 00H

Example:

| |
|---|
| Request: |
| 2AH, 61H, 00H, 05H, 01H, 02H, E4H, 88H, 0DH |
| Allow configuration. |
| response: |
| 2AH, 61H, 00H, 05H, 01H, 02H, 00H, 6CH, 0DH |
| Instruction received acknowledgement. |

Switching

Switching the protocol is done via a special instruction of Spinel (format 97) protocol. An exact address must be used with this instruction (broadcast or universal addresses are not allowed). This instruction has to follow “Allow configuration” instruction directly.

Request:

Instruction code: EDH

Parameters: (pid)

| pid | length: 1 byte |
|--|---|
| Protocol identification number. One of these can be used: | |
| 01H | – Spinel: both formats (66 ASCII and 97 binary) |
| 02H | – MODBUS RTU |
| 03H | – Drak3 |
| 04H | – Drak4 |
| 05H | – Spinel: only binary format 97 ¹¹ |
| If the device can't communicate via a given protocol, it will not be switched. | |

Response:

Acknowledgement code: ACK 00H

¹¹ This option is not available in older firmware versions.

Examples:

| |
|--|
| Request: |
| 2AH, 61H, 00H, 06H, 66H, 02H, EDH, 02H, 17H, 0DH |
| Instruction to switch from Spinel to ModBus RTU. |
| Response: |
| 2AH, 61H, 00H, 05H, 66H, 02H, 00H, 07H, 0DH |
| Instruction received OK. The device will communicate via ModBus RTU from now on. |

ADDITION A – HYSTERESIS

Hysteresis enables user to eliminate the fluctuation of the measured values. During measuring the measured value often happens to be unstable and it quickly fluctuates around the real value either naturally or due to the noise of the device.

In AD4 it is possible to set an upper and lower limit to be monitored. Exceeding the upper limit (or dropping below the lower limit) will result in an automatic message sent to the superior system by e-mail etc.

If the measured value fluctuates quickly around the upper or lower limit, the information about limit violations would be sent repeatedly even though the value does not change at all. This can be avoided by setting a so called hysteresis. It defines dead bands in which the information is not being sent.

The principle of the hysteresis is demonstrated in the following two charts showing temperature development.

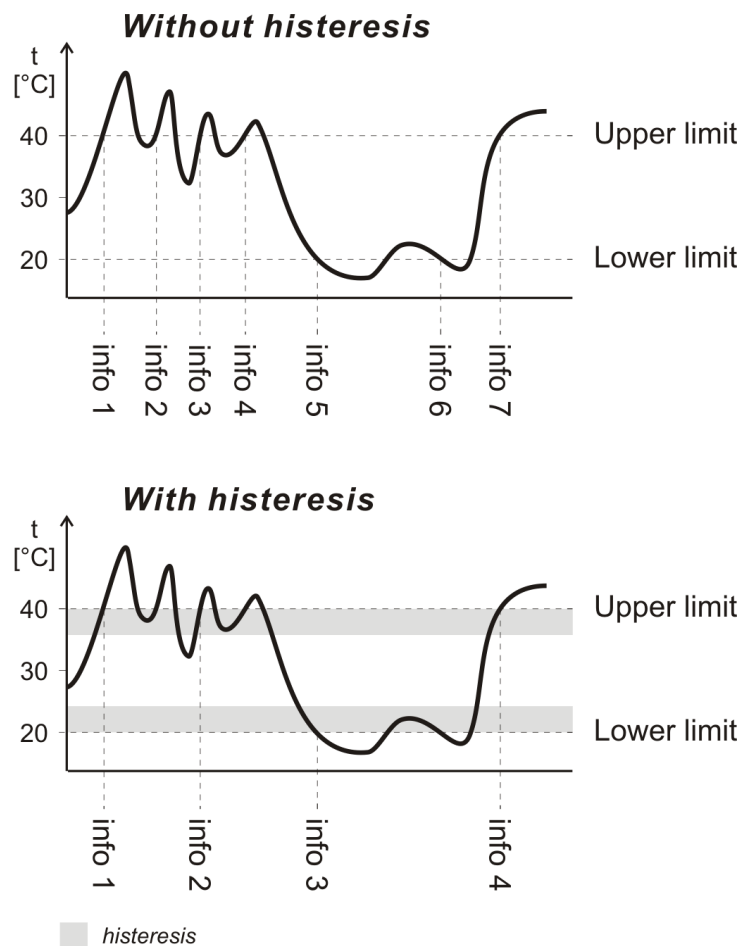


Fig. 1 – hysteresis of temperature limits

The hysteresis value applies below the upper limit (or above the lower limit) – see Fig. 1.

In the upper chart the hysteresis has been switched off (set to 0). The measured value fluctuates around the set limits causing frequent sending of relevant information to the superior system. If the hysteresis is set – like in the second chart – the information is sent only in case of a more significant change, but not just during the fluctuation of the value around the limit.

The hysteresis range needs to be chosen based on the measured value and the size of measured value fluctuation.

Papouch s.r.o.

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